

Package ‘gstat’

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Title geostatistical modelling, prediction and simulation

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Description variogram modelling; simple, ordinary and universal point
or block (co)kriging, sequential Gaussian or indicator
(co)simulation; variogram and variogram map plotting utility functions.

Depends R (>= 2.10), methods, sp (>= 0.9-72)

Imports lattice

Suggests rgdal (>= 0.5.2), fields, mapdata, lattice, spacetime, maptools

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coalash	<i>Coal ash samples from a mine in Pennsylvania</i>
---------	---

Description

Data obtained from Gomez and Hazen (1970, Tables 19 and 20) on coal ash for the Robena Mine Property in Greene County Pennsylvania.

Usage

```
data(coalash)
```

Format

This data frame contains the following columns:

- x** a numeric vector; x-coordinate; reference unknown
- y** a numeric vector; x-coordinate; reference unknown
- coalash** the target variable

Note

data are also present in package fields, as coalash.

Author(s)

unknown; R version prepared by Edzer Pebesma; data obtained from <http://www.stat.uiowa.edu/~dzimmer/spatialstats/>, Dale Zimmerman's course page

References

N.A.C. Cressie, 1993, Statistics for Spatial Data, Wiley.

Gomez, M. and Hazen, K. (1970). Evaluating sulfur and ash distribution in coal seams by statistical response surface regression analysis. U.S. Bureau of Mines Report RI 7377.

see also fields manual: <http://www.image.ucar.edu/GSP/Software/Fields/fields.manual.coalashEX.Krig.shtml>

Examples

```
data(coalash)
summary(coalash)
```

fit.lmc

Fit a Linear Model of Coregionalization to a Multivariable Sample Variogram

Description

Fit a Linear Model of Coregionalization to a Multivariable Sample Variogram; in case of a single variogram model (i.e., no nugget) this is equivalent to Intrinsic Correlation

Usage

```
fit.lmc(v, g, model, fit.ranges = FALSE, fit.lmc = !fit.ranges,
correct.diagonal = 1.0, ...)
```

Arguments

v	multivariable sample variogram, output of variogram
g	gstat object, output of gstat
model	variogram model, output of vgm ; if supplied this value is used as initial value for each fit
fit.ranges	logical; determines whether the range coefficients (excluding that of the nugget component) should be fitted; or logical vector: determines for each range parameter of the variogram model whether it should be fitted or fixed.
fit.lmc	logical; if TRUE, each coefficient matrices of partial sills is guaranteed to be positive definite

```
correct.diagonal
```

multiplicative correction factor to be applied to partial sills of direct variograms only; the default value, 1.0, does not correct. If you encounter problems with singular covariance matrices during cokriging or cosimulation, you may want to try to increase this to e.g. 1.01

```
...
```

parameters that get passed to [fit.variogram](#)

Value

returns an object of class `gstat`, with fitted variograms;

Note

This function does not use the iterative procedure proposed by M. Goulard and M. Voltz (Math. Geol., 24(3): 269-286; reproduced in Goovaerts' 1997 book) but uses simply two steps: first, each variogram model is fitted to a direct or cross variogram; next each of the partial sill coefficient matrices is approached by its in least squares sense closest positive definite matrices (by setting any negative eigenvalues to zero).

The argument `correct.diagonal` was introduced by experience: by zeroing the negative eigenvalues for fitting positive definite partial sill matrices, apparently still perfect correlation may result, leading to singular cokriging/cosimulation matrices. If someone knows of a more elegant way to get around this, please let me know.

Author(s)

Edzer Pebesma

References

<http://www.gstat.org/>

See Also

[variogram](#), [vgm](#), [fit.variogram](#), `demo(cokriging)`

`fit.variogram`

Fit a Variogram Model to a Sample Variogram

Description

Fit ranges and/or sills from a simple or nested variogram model to a sample variogram

Usage

```
fit.variogram(object, model, fit.sills = TRUE, fit.ranges = TRUE,
fit.method = 7, debug.level = 1, warn.if.neg = FALSE )
```

Arguments

<code>object</code>	sample variogram, output of variogram
<code>model</code>	variogram model, output of vgm
<code>fit.sills</code>	logical; determines whether the partial sill coefficients (including nugget variance) should be fitted; or logical vector: determines for each partial sill parameter whether it should be fitted or fixed.
<code>fit.ranges</code>	logical; determines whether the range coefficients (excluding that of the nugget component) should be fitted; or logical vector: determines for each range parameter whether it should be fitted or fixed.
<code>fit.method</code>	fitting method, used by <code>gstat</code> . The default method uses weights N_h/h^2 with N_h the number of point pairs and h the distance. This criterion is not supported by theory, but by practice. For other values of <code>fit.method</code> , see table 4.2 in the <code>gstat</code> manual.
<code>debug.level</code>	integer; set <code>gstat</code> internal debug level
<code>warn.if.neg</code>	logical; if TRUE a warning is issued whenever a sill value of a direct variogram becomes negative

Value

returns a fitted variogram model (of class `variogramModel`).

This is a data.frame has two attributes: (i) `singular` a logical attribute that indicates whether the non-linear fit converged, or ended in a singularity, and (ii) `SSErr` a numerical attribute with the (weighted) sum of squared errors of the fitted model. See Notes below.

Note

If fitting the range(s) is part of the job of this function, the results may well depend on the starting values, given in argument `model`. This is nothing new, but generally true for non-linear regression problems. This function uses the internal `gstat` (C) code, which iterates over (a) a direct (least squares) fit of the partial sills and (b) an iterated search, using gradients, for the optimal range value(s), until convergence of after a combined step ((a) and (b)) is reached.

If for a direct (i.e. not a cross) variogram a sill parameter (partial sill or nugget) becomes negative, `fit.variogram` is called again with this parameter set to zero, and with a FALSE flag to further fit this sill. This implies that once at the search space boundary, a sill value does not never away from it.

On singular model fits: If your variogram turns out to be a flat, horizontal or sloping line, then fitting a three parameter model such as the exponential or spherical with nugget is a bit heavy: there's an infinite number of possible combinations of sill and range (both very large) to fit to a sloping line. In this case, the returned, singular model may still be useful: just try and plot it. `Gstat` converges when the parameter values stabilize, and this may not be the case. Another case of singular model fits happens when a model that reaches the sill (such as the spherical) is fit with a nugget, and the range parameter starts, or converges to a value smaller than the distance of the second sample variogram estimate. In this case, again, an infinite number of possibilities occur essentially for fitting a line through a single (first sample variogram) point. In both cases, fixing one or more of the variogram model parameters may help you out.

Author(s)

Edzer Pebesma

References<http://www.gstat.org/>

Pebesma, E.J., 2004. Multivariable geostatistics in S: the gstat package. *Computers & Geosciences*, 30: 683-691.

See Also[variogram](#), [vgm](#)**Examples**

```
data(meuse)
vgm1 <- variogram(log(zinc)~1, ~x+y, meuse)
fit.variogram(vgm1, vgm(1, "Sph", 300, 1))
```

```
fit.variogram.gls
```

GLS fitting of variogram parameters

Description

Fits variogram parameters (nugget, sill, range) to variogram cloud, using GLS (generalized least squares) fitting. Only for direct variograms.

Usage

```
fit.variogram.gls(formula, data, model, maxiter = 30,
eps = .01, trace = TRUE, ignoreInitial = TRUE, cutoff = Inf,
plot = FALSE)
```

Arguments

formula	formula defining the response vector and (possible) regressors; in case of absence of regressors, use e.g. <code>z~1</code>
data	object of class <code>Spatial</code>
model	variogram model to be fitted, output of <code>vgm</code>
maxiter	maximum number of iterations
eps	convergence criterium
trace	logical; if TRUE, prints parameter trace
ignoreInitial	logical; if FALSE, initial parameter are taken from model; if TRUE, initial values of model are ignored and taken from variogram cloud: nugget: $\text{mean}(y) / 2$, sill: $\text{mean}(y) / 2$, range $\text{median}(h_0) / 4$ with y the semivariance cloud value and h_0 the distances

cutoff	maximum distance up to which point pairs are taken into consideration
plot	logical; if TRUE, a plot is returned with variogram cloud and fitted model; else, the fitted model is returned.

Value

an object of class "variogramModel"; see [fit.variogram](#); if `plot` is TRUE, a plot is returned instead.

Note

Inspired by the code of Mihael Drinovac, which was again inspired by code from Ernst Glatzer, author of package `vardiag`.

Author(s)

Edzer Pebesma

References

Mueller, W.G., 1999: Least-squares fitting from the variogram cloud. *Statistics & Probability Letters*, 43, 93-98.

Mueller, W.G., 2007: *Collecting Spatial Data*. Springer, Heidelberg.

See Also

[fit.variogram](#),

Examples

```
data(meuse)
coordinates(meuse) = ~x+y
fit.variogram.gls(log(zinc)~1, meuse[1:40,], vgm(1, "Sph", 900,1))
```

`fit.variogram.reml` *REML Fit Direct Variogram Partial Sills to Data*

Description

Fit Variogram Sills to Data, using REML (only for direct variograms; not for cross variograms)

Usage

```
fit.variogram.reml(formula, locations, data, model, debug.level = 1, set, degree =
```

Arguments

<code>formula</code>	formula defining the response vector and (possible) regressors; in case of absence of regressors, use e.g. <code>z~1</code>
<code>locations</code>	spatial data locations; a formula with the coordinate variables in the right hand (dependent variable) side.
<code>data</code>	data frame where the names in formula and locations are to be found
<code>model</code>	variogram model to be fitted, output of <code>vgm</code>
<code>debug.level</code>	debug level; set to 65 to see the iteration trace and log likelihood
<code>set</code>	additional options that can be set; use <code>set=list(iter=100)</code> to set the max. number of iterations to 100.
<code>degree</code>	order of trend surface in the location, between 0 and 3

Value

an object of class "variogramModel"; see [fit.variogram](#)

Note

This implementation only uses REML fitting of sill parameters. For each iteration, an $n \times n$ matrix is inverted, with n the number of observations, so for large data sets this method becomes demanding. I guess there is much more to likelihood variogram fitting in package `geoR`, and probably also in `nlme`.

Author(s)

Edzer Pebesma

References

Christensen, R. Linear models for multivariate, Time Series, and Spatial Data, Springer, NY, 1991.
 Kitanidis, P., Minimum-Variance Quadratic Estimation of Covariances of Regionalized Variables, *Mathematical Geology* 17 (2), 195–208, 1985

See Also

[fit.variogram](#),

Examples

```
data(meuse)
fit.variogram.reml(log(zinc)~1, ~x+y, meuse, model = vgm(1, "Sph", 900,1))
```

fulmar*Fulmaris glacialis data*

Description

Airborne counts of *Fulmaris glacialis* during the Aug/Sept 1998 and 1999 flights on the Netherlands part of the North Sea (NCP).

Usage

```
data(fulmar)
```

Format

This data frame contains the following columns:

year year of measurement: 1998 or 1999

x x-coordinate in UTM31

y y-coordinate in UTM31

depth sea water depth, in m

coast distance to coast, in m

fulmar observed density (number of birds per square km)

Author(s)

Dutch National Institute for Coastal and Marine Management (RIKZ), <http://www.rikz.nl/>

See Also

[ncp.grid](#)

E.J. Pebesma, R.N.M. Duin, P.A. Burrough, 2005. Mapping Sea Bird Densities over the North Sea: Spatially Aggregated Estimates and Temporal Changes. *Environmetrics* 16, (6), p 573-587.

Examples

```
data(fulmar)
summary(fulmar)
```

get.contr

Calculate contrasts from multivariable predictions

Description

Given multivariable predictions and prediction (co)variances, calculate contrasts and their (co)variance

Usage

```
get.contr(data, gstat.object, X, ids = names(gstat.object$data))
```

Arguments

data	data frame, output of predict.gstat
gstat.object	object of class gstat, used to extract ids; may be missing if ids is used
X	contrast vector or matrix; the number of variables in gstat.object should equal the number of elements in X if X is a vector, or the number of rows in X if X is a matrix.
ids	character vector with (selection of) id names, present in data

Details

From data, we can extract the $n \times 1$ vector with multivariable predictions, say y , and its $n \times n$ covariance matrix V . Given a contrast matrix in X , this function computes the contrast vector $C=X'y$ and its variance $Var(C)=X'V X$.

Value

a data frame containing for each row in data the generalized least squares estimates (named beta.1, beta.2, ...), their variances (named var.beta.1, var.beta.2, ...) and covariances (named cov.beta.1.2, cov.beta.1.3, ...)

Author(s)

Edzer Pebesma

References

<http://www.gstat.org/>

See Also

[predict.gstat](#)

gstat

*Create gstat objects, or subset it***Description**

Function that creates gstat objects; objects that hold all the information necessary for univariate or multivariate geostatistical prediction (simple, ordinary or universal (co)kriging), or its conditional or unconditional Gaussian or indicator simulation equivalents. Multivariate gstat object can be subsetted.

Usage

```
gstat(g, id, formula, locations, data, model = NULL, beta, nmax = Inf,
      nmin = 0, maxdist = Inf, dummy = FALSE, set, fill.all = FALSE,
      fill.cross = TRUE, variance = "identity", weights = NULL, merge,
      degree = 0, vdist = FALSE, lambda = 1.0)
## S3 method for class 'gstat'
print(x, ...)
```

Arguments

<code>g</code>	gstat object to append to; if missing, a new gstat object is created
<code>id</code>	identifier of new variable; if missing, <code>varn</code> is used with <code>n</code> the number for this variable. If a cross variogram is entered, <code>id</code> should be a vector with the two <code>id</code> values, e.g. <code>c("zn", "cd")</code> , further only supplying arguments <code>g</code> and <code>model</code> . It is advisable not to use expressions, such as <code>log(zinc)</code> , as identifiers, as this may lead to complications later on.
<code>formula</code>	formula that defines the dependent variable as a linear model of independent variables; suppose the dependent variable has name <code>z</code> , for ordinary and simple kriging use the formula <code>z~1</code> ; for simple kriging also define <code>beta</code> (see below); for universal kriging, suppose <code>z</code> is linearly dependent on <code>x</code> and <code>y</code> , use the formula <code>z~x+y</code>
<code>locations</code>	formula with only independent variables that define the spatial data locations (coordinates), e.g. <code>~x+y</code> ; if <code>data</code> has a <code>coordinates</code> method to extract its coordinates this argument can be ignored (see package <code>sp</code> for classes for point or grid data).
<code>data</code>	data frame; contains the dependent variable, independent variables, and locations.
<code>model</code>	variogram model for this <code>id</code> ; defined by a call to vgm ; see argument <code>id</code> to see how cross variograms are entered
<code>beta</code>	only for simple kriging (and simulation based on simple kriging); vector with the trend coefficients (including intercept); if no independent variables are defined the model only contains an intercept and this should be the simple kriging mean
<code>nmax</code>	for local kriging: the number of nearest observations that should be used for a kriging prediction or simulation, where nearest is defined in terms of the space of the spatial locations

<code>nmin</code>	for local kriging: if the number of nearest observations within distance <code>maxdist</code> is less than <code>nmin</code> , a missing value will be generated; see <code>maxdist</code>
<code>maxdist</code>	for local kriging: only observations within a distance of <code>maxdist</code> from the prediction location are used for prediction or simulation; if combined with <code>nmax</code> , both criteria apply
<code>dummy</code>	logical; if TRUE, consider this data as a dummy variable (only necessary for unconditional simulation)
<code>set</code>	named list with optional parameters to be passed to <code>gstat</code> (only <code>set</code> commands of <code>gstat</code> are allowed, and not all of them may be relevant; see the manual for <code>gstat</code> stand-alone, URL below)
<code>x</code>	<code>gstat</code> object to print
<code>fill.all</code>	logical; if TRUE, fill all of the direct variogram and, depending on the value of <code>fill.cross</code> also all cross variogram model slots in <code>g</code> with the given variogram model
<code>fill.cross</code>	logical; if TRUE, fill all of the cross variograms, if FALSE fill only all direct variogram model slots in <code>g</code> with the given variogram model (only if <code>fill.all</code> is used)
<code>variance</code>	character; variance function to transform to non-stationary covariances; "identity" does not transform, other options are "mu" (Poisson) and "mu(1-mu)" (binomial)
<code>weights</code>	numeric vector; if present, covariates are present, and variograms are missing weights are passed to OLS prediction routines resulting in WLS; if variograms are given, weights should be 1/variance, where variance specifies location-specific measurement error; see references section below
<code>merge</code>	either character vector of length 2, indicating two ids that share a common mean; the more general <code>gstat</code> merging of any two coefficients across variables is obtained when a list is passed, with each element a character vector of length 4, in the form <code>c("id1", 1, "id2", 2)</code> . This merges the first parameter for variable <code>id1</code> to the second of variable <code>id2</code> .
<code>degree</code>	order of trend surface in the location, between 0 and 3
<code>vdist</code>	logical; if TRUE, instead of Euclidian distance variogram distance is used for selecting the <code>nmax</code> nearest neighbours, after observations within distance <code>maxdist</code> (Euclidian/geographic) have been pre-selected
<code>lambda</code>	test feature; doesn't do anything (yet)
<code>...</code>	arguments that are passed to the printing of variogram models only

Details

to print the full contents of the object `g` returned, use `as.list(g)` or `print.default(g)`

Value

an object of class `gstat`, which inherits from `list`. Its components are:

<code>data</code>	list; each element is a list with the formula, locations, data, <code>nvars</code> , <code>beta</code> , etc., for a variable
-------------------	---

<code>model</code>	list; each element contains a variogram model; names are those of the elements of data; cross variograms have names of the pairs of data elements, separated by a . (e.g.: <code>var1.var2</code>)
<code>set</code>	list; named list, corresponding to <code>set name=value</code> ; gstat commands (look up the set command in the gstat manual for a full list)

Note

The function currently copies the data objects into the gstat object, so this may become a large object. I would like to copy only the name of the data frame, but could not get this to work. Any help is appreciated.

Subsetting (see examples) is done using the `id`'s of the variables, or using numeric subsets. Sub-setted gstat objects only contain cross variograms if (i) the original gstat object contained them and (ii) the order of the subset indexes increases, numerically, or given the order they have in the gstat object.

The merge item may seem obscure. Still, for colocated cokriging, it is needed. See texts by Goovaerts, Wackernagel, Chiles and Delfiner, or look for standardised ordinary kriging in the 1992 Deutsch and Journel or Isaaks and Srivastava. In these cases, two variables share a common mean parameter. Gstat generalises this case: any two variables may share any of the regression coefficients; allowing for instance analysis of covariance models, when variograms were left out (see e.g. R. Christensen's "Plane answers" book on linear models). The tests directory of the package contains examples in file `merge.R`. There is also `demo(pcb)` which merges slopes across years, but with year-dependent intercept.

Author(s)

Edzer Pebesma

References

<http://www.gstat.org/> Pebesma, E.J., 2004. Multivariable geostatistics in S: the gstat package. Computers & Geosciences, 30: 683-691.

for kriging with known, varying measurement errors (`weights`), see e.g. Delhomme, J.P. Kriging in the hydrosociences. Advances in Water Resources, 1(5):251-266, 1978; see also the section Kriging with known measurement errors in the gstat user's manual, <http://www.gstat.org/>

See Also

[predict.gstat](#), [krige](#)

Examples

```
data(meuse)
# let's do some manual fitting of two direct variograms and a cross variogram
g <- gstat(id = "ln.zinc", formula = log(zinc)~1, locations = ~x+y,
data = meuse)
g <- gstat(g, id = "ln.lead", formula = log(lead)~1, locations = ~x+y,
```

```

data = meuse)
# examine variograms and cross variogram:
plot(variogram(g))
# enter direct variograms:
g <- gstat(g, id = "ln.zinc", model = vgm(.55, "Sph", 900, .05))
g <- gstat(g, id = "ln.lead", model = vgm(.55, "Sph", 900, .05))
# enter cross variogram:
g <- gstat(g, id = c("ln.zinc", "ln.lead"), model = vgm(.47, "Sph", 900, .03))
# examine fit:
plot(variogram(g), model = g$model, main = "models fitted by eye")
# see also demo(cokriging) for a more efficient approach
g["ln.zinc"]
g["ln.lead"]
g[c("ln.zinc", "ln.lead")]
g[1]
g[2]

# Inverse distance interpolation with inverse distance power set to .5:
# (kriging variants need a variogram model to be specified)
data(meuse)
data(meuse.grid)
meuse.gstat <- gstat(id = "zinc", formula = zinc ~ 1, locations = ~ x + y,
data = meuse, nmax = 7, set = list(idp = .5))
meuse.gstat
z <- predict(meuse.gstat, meuse.grid)
library(lattice) # for levelplot
levelplot(zinc.pred~x+y, z, aspect = "iso")
# see demo(cokriging) and demo(examples) for further examples,
# and the manuals for predict.gstat and image

```

hscat

Produce h-scatterplot

Description

Produces h-scatterplots, where point pairs having specific separation distances are plotted. This function is a wrapper around xyplot.

Usage

```
hscat(formula, data, breaks, pch = 3, cex = .6, mirror = FALSE,
variogram.alpha = 0, ...)
```

Arguments

formula	specifies the dependent variable
data	data where the variable in formula is resolved
breaks	distance class boundaries

pch	plotting symbol
cex	plotting symbol size
mirror	logical; duplicate all points mirrored along x=y? (note that correlations are those of the points plotted)
variogram.alpha	parameter to be passed as alpha parameter to variogram ; if alpha is specified it will only affect xyplot by being passed through ...
...	parameters, passed to variogram and xyplot

Value

an object of class trellis; normally the h scatter plot

Note

Data pairs are plotted once, so the h-scatterplot are not symmetric.

Author(s)

Edzer Pebesma

References

<http://www.gstat.org/>

Pebesma, E.J., 2004. Multivariable geostatistics in S: the gstat package. Computers & Geosciences, 30: 683-691.

Examples

```
data(meuse)
coordinates(meuse) = ~x+y
hscat(log(zinc)~1, meuse, c(0, 80, 120, 250, 500, 1000))
```

image

Image Gridded Coordinates in Data Frame

Description

Image gridded data, held in a data frame, keeping the right aspect ratio for axes, and the right cell shape

Usage

```
## S3 method for class 'data.frame'
image(x, zcol = 3, xcol = 1, ycol = 2, asp = 1, ...)
xyz2img(xyz, zcol = 3, xcol = 1, ycol = 2, tolerance = 10 * .Machine$double.eps)
```

Arguments

<code>x</code>	data frame (or matrix) with x-coordinate, y-coordinate, and z-coordinate in its columns
<code>zcol</code>	column number or name of z-variable
<code>xcol</code>	column number or name of x-coordinate
<code>ycol</code>	column number or name of y-coordinate
<code>asp</code>	aspect ratio for the x and y axes
<code>...</code>	arguments, passed to <code>image.default</code>
<code>xyz</code>	data frame (same as <code>x</code>)
<code>tolerance</code>	maximum allowed deviation for coordinates from being exactly on a regularly spaced grid

Value

`image.data.frame` plots an image from gridded data, organized in arbitrary order, in a data frame. It uses `xyz2img` and `image.default` for this. In the S-Plus version, `xyz2img` tries to make an image object with a size such that it will plot with an equal aspect ratio; for the R version, `image.data.frame` uses the `asp=1` argument to guarantee this.

`xyz2img` returns a list with components: `z`, a matrix containing the z-values; `x`, the increasing coordinates of the rows of `z`; `y`, the increasing coordinates of the columns of `z`. This list is suitable input to `image.default`.

Note

I wrote this function before I found out about `levelplot`, a Lattice/Trellis function that lets you control the aspect ratio by the `aspect` argument, and that automatically draws a legend, and therefore I now prefer `levelplot` over `image`. Plotting points on a `levelplots` is probably done with providing a panel function and using `lpoints`.

(for S-Plus only –) it is hard (if not impossible) to get exactly right cell shapes (e.g., square for a square grid) without altering the size of the plotting region, but this function tries hard to do so by extending the image to plot in either x- or y-direction. The larger the grid, the better the approximation. Geographically correct images can be obtained by modifying `par("pin")`. Read the examples, image a 2 x 2 grid, and play with `par("pin")` if you want to learn more about this.

Author(s)

Edzer Pebesma

Examples

```
data(meuse)
data(meuse.grid)
g <- gstat(formula=log(zinc)~1,locations=~x+y,data=meuse,model=vgm(1,"Exp",300))
x <- predict(g, meuse.grid)
image(x, 4, main="kriging variance and data points")
points(meuse$x, meuse$y, pch = "+")
# non-square cell test:
```



```

image(x[((x$y - 20) %% 80) == 0,], main = "40 x 80 cells")
image(x[((x$x - 20) %% 80) == 0,], main = "80 x 40 cells")
# the following works for square cells only:
oldpin <- par("pin")
ratio <- length(unique(x$x))/length(unique(x$y))
par(pin = c(oldpin[2]*ratio,oldpin[2]))
image(x, main="Exactly square cells, using par(pin)")
par(pin = oldpin)
library(lattice)
levelplot(var1.var~x+y, x, aspect = "iso", main = "kriging variance")

```

jura

Jura data set

Description

The jura data set from Pierre Goovaerts book (see references below). It contains four data.frames: prediction.dat, validation.dat and transect.dat and juragrid.dat, and three data.frames with consistently coded land use and rock type factors. The examples below show how to transform these into spatial (sp) objects.

Usage

```
data(jura)
```

Format

This data frame contains the following columns:

Xloc see book

Yloc see book

Landuse see book and below

Rock see book and below

Cd see book

Co see book

Cr see book

Cu see book

Ni see book

Pb see book

Zn see book

Note

The points data sets were obtained from <http://home.comcast.net/~goovaerts/book.html>, the grid data were kindly provided by Pierre Goovaerts.

Rock Types: 1: Argovian, 2: Kimmeridgian, 3: Sequanian, 4: Portlandian, 5: Quaternary.

Land uses: 1: Forest, 2: Pasture (Weide(land), Wiese, Grasland), 3: Meadow (Wiese, Flur, Matte, Anger), 4: Tillage (Ackerland, bestelltes Land)

Points 22 and 100 in the validation set (`validation.dat[c(22,100),]`) seem not to lie exactly on the grid originally intended, but are kept as such to be consistent with the book.

Author(s)

Data preparation by David Rossiter (rossiter@itc.nl) and Edzer Pebesma

References

Goovaerts, P. 1997. Geostatistics for Natural Resources Evaluation. Oxford Univ. Press, New-York, 483 p. Appendix C describes (and gives) the Jura data set.

Atteia, O., Dubois, J.-P., Webster, R., 1994, Geostatistical analysis of soil contamination in the Swiss Jura: Environmental Pollution 86, 315-327

Webster, R., Atteia, O., Dubois, J.-P., 1994, Coregionalization of trace metals in the soil in the Swiss Jura: European Journal of Soil Science 45, 205-218

Examples

```
data(jura)
summary(prediction.dat)
summary(validation.dat)
summary(transect.dat)
summary(juragrid.dat)

# the commands to create the spatial objects:
require(sp)
jura.pred = prediction.dat
jura.val = validation.dat
jura.grid = juragrid.dat

jura.pred$Landuse = factor(prediction.dat$Landuse, labels=levels(juragrid.dat$Landuse))
jura.pred$Rock = factor(prediction.dat$Rock, labels=levels(juragrid.dat$Rock))
jura.val$Landuse = factor(validation.dat$Landuse, labels=levels(juragrid.dat$Landuse))
jura.val$Rock = factor(validation.dat$Rock, labels=levels(juragrid.dat$Rock))

coordinates(jura.pred) = ~Xloc+Yloc
coordinates(jura.val) = ~Xloc+Yloc
coordinates(jura.grid) = ~Xloc+Yloc
gridded(jura.grid) = TRUE
```

krige	<i>Simple, Ordinary or Universal, global or local, Point or Block Kriging, or simulation.</i>
-------	---

Description

Function for simple, ordinary or universal kriging (sometimes called external drift kriging), kriging in a local neighbourhood, point kriging or kriging of block mean values (rectangular or irregular blocks), and conditional (Gaussian or indicator) simulation equivalents for all kriging varieties, and function for inverse distance weighted interpolation. For multivariable prediction, see [gstat](#) and [predict.gstat](#)

Usage

```
krige(formula, locations, ...)
krige.locations(formula, locations, data, newdata, model, ..., beta, nmax
= Inf, nmin = 0, maxdist = Inf, block, nsim = 0, indicators = FALSE,
na.action = na.pass, debug.level = 1)
krige.spatial(formula, locations, newdata, model, ..., beta, nmax
= Inf, nmin = 0, maxdist = Inf, block, nsim = 0, indicators = FALSE,
na.action = na.pass, debug.level = 1)
krige0(formula, data, newdata, model, beta, y, ..., computeVar = FALSE,
fullCovariance = FALSE)
krigeST(formula, data, newdata, modelList, y, ..., computeVar = FALSE,
fullCovariance = FALSE)
idw(formula, locations, ...)
idw.locations(formula, locations, data, newdata, nmax = Inf,
nmin = 0, maxdist = Inf, block, na.action = na.pass, idp = 2.0,
debug.level = 1)
idw.spatial(formula, locations, newdata, nmax = Inf, nmin = 0,
maxdist = Inf, block = numeric(0), na.action = na.pass, idp = 2.0,
debug.level = 1)
idw0(formula, data, newdata, y)
```

Arguments

formula	formula that defines the dependent variable as a linear model of independent variables; suppose the dependent variable has name <i>z</i> , for ordinary and simple kriging use the formula <i>z~1</i> ; for simple kriging also define <i>beta</i> (see below); for universal kriging, suppose <i>z</i> is linearly dependent on <i>x</i> and <i>y</i> , use the formula <i>z~x+y</i>
locations	object of class <code>Spatial</code> , or (deprecated) formula defines the spatial data locations (coordinates) such as <i>~x+y</i>
data	data frame: should contain the dependent variable, independent variables, and coordinates, should be missing if locations contains data.

<code>newdata</code>	data frame or Spatial object with prediction/simulation locations; should contain attribute columns with the independent variables (if present) and (if locations is a formula) the coordinates with names as defined in <code>locations</code>
<code>model</code>	variogram model of dependent variable (or its residuals), defined by a call to <code>vgm</code> or <code>fit.variogram</code> ; for <code>krige0</code> also a user-supplied covariance function is allowed (see example below)
<code>modelList</code>	list with two named elements: <code>space</code> and <code>time</code> ; these should either be the output of <code>vgm</code> , or user-defined covariance functions that takes one or two ST objects
<code>beta</code>	for simple kriging (and simulation based on simple kriging): vector with the trend coefficients (including intercept); if no independent variables are defined the model only contains an intercept and <code>beta</code> should be the simple kriging mean
<code>nmax</code>	for local kriging: the number of nearest observations that should be used for a kriging prediction or simulation, where nearest is defined in terms of the space of the spatial locations. By default, all observations are used
<code>nmin</code>	for local kriging: if the number of nearest observations within distance <code>maxdist</code> is less than <code>nmin</code> , a missing value will be generated; see <code>maxdist</code>
<code>maxdist</code>	for local kriging: only observations within a distance of <code>maxdist</code> from the prediction location are used for prediction or simulation; if combined with <code>nmax</code> , both criteria apply
<code>block</code>	block size; a vector with 1, 2 or 3 values containing the size of a rectangular in x-, y- and z-dimension respectively (0 if not set), or a data frame with 1, 2 or 3 columns, containing the points that discretize the block in the x-, y- and z-dimension to define irregular blocks relative to (0,0) or (0,0,0)—see also the details section of <code>predict.gstat</code> . By default, predictions or simulations refer to the support of the data values.
<code>nsim</code>	integer; if set to a non-zero value, conditional simulation is used instead of kriging interpolation. For this, sequential Gaussian or indicator simulation is used (depending on the value of <code>indicators</code>), following a single random path through the data.
<code>indicators</code>	logical, only relevant if <code>nsim</code> is non-zero; if TRUE, use indicator simulation; else use Gaussian simulation
<code>na.action</code>	function determining what should be done with missing values in 'newdata'. The default is to predict 'NA'. Missing values in coordinates and predictors are both dealt with.
<code>debug.level</code>	debug level, passed to <code>predict.gstat</code> ; use -1 to see progress in percentage, and 0 to suppress all printed information
<code>...</code>	other arguments that will be passed to <code>gstat</code>
<code>idp</code>	numeric; specify the inverse distance weighting power
<code>y</code>	matrix; to kriging multiple fields in a single step, pass data as columns of matrix <code>y</code> . This will ignore the value of the response in <code>formula</code> .
<code>computeVar</code>	logical; if TRUE, prediction variances will be returned
<code>fullCovariance</code>	logical; if FALSE a vector with prediction variances will be returned, if TRUE the full covariance matrix of all predictions will be returned

Details

Function `krige` is a simple wrapper method around `gstat` and `predict.gstat` for univariate kriging prediction and conditional simulation methods available in `gstat`. For multivariate prediction or simulation, or for other interpolation methods provided by `gstat` (such as inverse distance weighted interpolation or trend surface interpolation) use the functions `gstat` and `predict.gstat` directly.

Function `idw` performs just as `krige` without a model being passed, but allows direct specification of the inverse distance weighting power. Don't use with predictors in the formula.

For further details, see `predict.gstat`.

Value

if `locations` is not a formula, object of the same class as `newdata` (deriving from `Spatial`); else a data frame containing the coordinates of `newdata`. Attributes `columns` contain prediction and prediction variance (in case of kriging) or the `abs (nsim)` columns of the conditional Gaussian or indicator simulations

`krige0` and `idw0` are alternative functions that have reduced functionality and larger memory requirements; they return numeric vectors (or matrices, in case of multiple dependent) with predicted values only; in case `computeVar` is `TRUE`, a list with elements `pred` and `var` is returned, containing predictions, and (co)variances (depending on argument `fullCovariance`).

Methods

formula = "formula", locations = "formula" `locations` specifies which coordinates in `data` refer to spatial coordinates

formula = "formula", locations = "Spatial" Object `locations` knows about its own spatial locations

formula = "formula", locations = "NULL" used in case of unconditional simulations; `newdata` needs to be of class `Spatial`

Note

Daniel G. Krige is a South African scientist who was a mining engineer when he first used generalised least squares prediction with spatial covariances in the 50's. George Matheron coined the term `kriging` in the 60's for the action of doing this, although very similar approaches had been taken in the field of meteorology. Beside being Krige's name, I consider "krige" to be to "kriging" what "predict" is to "prediction".

Author(s)

Edzer Pebesma

References

N.A.C. Cressie, 1993, Statistics for Spatial Data, Wiley.

<http://www.gstat.org/>

Pebesma, E.J., 2004. Multivariable geostatistics in S: the `gstat` package. *Computers & Geosciences*, 30: 683-691.

See Also

[gstat](#), [predict.gstat](#)

Examples

```
data(meuse)
coordinates(meuse) = ~x+y
data(meuse.grid)
gridded(meuse.grid) = ~x+y
m <- vgm(.59, "Sph", 874, .04)
# ordinary kriging:
x <- krige(log(zinc)~1, meuse, meuse.grid, model = m)
spplot(x["var1.pred"], main = "ordinary kriging predictions")
spplot(x["var1.var"], main = "ordinary kriging variance")
# simple kriging:
x <- krige(log(zinc)~1, meuse, meuse.grid, model = m, beta = 5.9)
# residual variogram:
m <- vgm(.4, "Sph", 954, .06)
# universal block kriging:
x <- krige(log(zinc)~x+y, meuse, meuse.grid, model = m, block = c(40,40))
spplot(x["var1.pred"], main = "universal kriging predictions")

# krige0, using user-defined covariance function and multiple responses in y:
# exponential variogram with range 500, defined as covariance function:
v = function(x,y) { exp(-spDists(coordinates(x),coordinates(y))/500) }
# krige two variables in a single pass (using 1 covariance model):
y = cbind(meuse$zinc,meuse$copper,meuse$lead,meuse$cadmium)
x <- krige0(zinc~1, meuse, meuse.grid, v, y = y)
meuse.grid$zinc = x[,1]
spplot(meuse.grid["zinc"], main = "zinc")
meuse.grid$copper = x[,2]
spplot(meuse.grid["copper"], main = "copper")
```

krige.cv

(co)kriging cross validation, n-fold or leave-one-out

Description

Cross validation functions for simple, ordinary or universal point (co)kriging, kriging in a local neighbourhood.

Usage

```
gstat.cv(object, nfold, remove.all = FALSE, verbose = FALSE,
all.residuals = FALSE, ...)
krige.cv(formula, locations, ...)
krige.cv.locations(formula, locations, data, model = NULL, ..., beta = NULL, nmax =
nmin = 0, maxdist = Inf, nfold = nrow(data), verbose = TRUE, debug.level = 0)
krige.cv.spatial(formula, locations, model = NULL, ..., beta = NULL, nmax = Inf,
nmin = 0, maxdist = Inf, nfold = nrow(locations), verbose = TRUE, debug.level = 0)
```

Arguments

<code>object</code>	object of class <code>gstat</code> ; see function gstat
<code>nfold</code>	integer; if larger than 1, then apply n-fold cross validation; if <code>nfold</code> equals <code>nrow(data)</code> (the default), apply leave-one-out cross validation; if set to e.g. 5, five-fold cross validation is done. To specify the folds, pass an integer vector of length <code>nrow(data)</code> with fold indexes.
<code>remove.all</code>	logical; if TRUE, remove observations at cross validation locations not only for the first, but for all subsequent variables as well
<code>verbose</code>	logical; if FALSE, progress bar is suppressed
<code>all.residuals</code>	logical; if TRUE, residuals for all variables are returned instead of for the first variable only
<code>...</code>	other arguments that will be passed to predict.gstat in case of <code>gstat.cv</code> , or to gstat in case of <code>krige.cv</code>
<code>formula</code>	formula that defines the dependent variable as a linear model of independent variables; suppose the dependent variable has name <code>z</code> , for ordinary and simple kriging use the formula <code>z~1</code> ; for simple kriging also define <code>beta</code> (see below); for universal kriging, suppose <code>z</code> is linearly dependent on <code>x</code> and <code>y</code> , use the formula <code>z~x+y</code>
<code>locations</code>	formula with only independent variables that define the spatial data locations (coordinates), e.g. <code>~x+y</code> , OR data object deriving from class <code>Spatial</code> , which has a <code>coordinates</code> method to extract its coordinates.
<code>data</code>	data frame; should contain the dependent variable, independent variables, and coordinates; only to be provided if <code>locations</code> is a formula
<code>model</code>	variogram model of dependent variable (or its residuals), defined by a call to vgm or fit.variogram
<code>beta</code>	only for simple kriging (and simulation based on simple kriging); vector with the trend coefficients (including intercept); if no independent variables are defined the model only contains an intercept and this should be the simple kriging mean
<code>nmax</code>	for local kriging: the number of nearest observations that should be used for a kriging prediction or simulation, where nearest is defined in terms of the space of the spatial locations. By default, all observations are used
<code>nmin</code>	for local kriging: if the number of nearest observations within distance <code>maxdist</code> is less than <code>nmin</code> , a missing value will be generated; see <code>maxdist</code>
<code>maxdist</code>	for local kriging: only observations within a distance of <code>maxdist</code> from the prediction location are used for prediction or simulation; if combined with <code>nmax</code> , both criteria apply
<code>debug.level</code>	print debugging information; 0 suppresses debug information

Details

Leave-one-out cross validation (LOOCV) visits a data point, and predicts the value at that location by leaving out the observed value, and proceeds with the next data point. (The observed value is left out because kriging would otherwise predict the value itself.) N-fold cross validation makes a

partitions the data set in N parts. For all observation in a part, predictions are made based on the remaining $N-1$ parts; this is repeated for each of the N parts. N -fold cross validation may be faster than LOOCV.

Value

data frame containing the coordinates of data or those of the first variable in `object`, and columns of prediction and prediction variance of cross validated data points, observed values, residuals, `zscore` (residual divided by kriging standard error), and `fold`.

If `all.residuals` is true, a data frame with residuals for all variables is returned, without coordinates.

Methods

formula = "formula", locations = "formula" locations specifies which coordinates in data refer to spatial coordinates

formula = "formula", locations = "Spatial" Object locations knows about its own spatial locations

Note

Leave-one-out cross validation seems to be much faster in plain (stand-alone) `gstat`, apparently quite a bit of the effort is spent moving data around from R to `gstat`.

Author(s)

Edzer Pebesma

References

<http://www.gstat.org/>

See Also

[krige](#), [gstat](#), [predict.gstat](#)

Examples

```
data(meuse)
coordinates(meuse) <- ~x+y
m <- vgm(.59, "Sph", 874, .04)
# five-fold cross validation:
x <- krige.cv(log(zinc)~1, meuse, m, nmax = 40, nfold=5)
bubble(x, "residual", main = "log(zinc): 5-fold CV residuals")

# multivariable; thanks to M. Rufino:
meuse.g <- gstat(id = "zn", formula = log(zinc) ~ 1, data = meuse)
meuse.g <- gstat(meuse.g, "cu", log(copper) ~ 1, meuse)
meuse.g <- gstat(meuse.g, model = vgm(1, "Sph", 900, 1), fill.all = TRUE)
x <- variogram(meuse.g, cutoff = 1000)
```



```

meuse.fit = fit.lmc(x, meuse.g)
out = gstat.cv(meuse.fit, nmax = 40, nfold = 5)
summary(out)
out = gstat.cv(meuse.fit, nmax = 40, nfold = c(rep(1,100), rep(2,55)))
summary(out)
# mean error, ideally 0:
mean(out$residual)
# MSPE, ideally small
mean(out$residual^2)
# Mean square normalized error, ideally close to 1
mean(out$zscore^2)
# correlation observed and predicted, ideally 1
cor(out$observed, out$observed - out$residual)
# correlation predicted and residual, ideally 0
cor(out$observed - out$residual, out$residual)

```

krigeTg

*TransGaussian kriging using Box-Cox transforms***Description**

TransGaussian (ordinary) kriging function using Box-Cox transforms

Usage

```

krigeTg(formula, locations, newdata, model = NULL, ...,
nmax = Inf, nmin = 0, maxdist = Inf, block = numeric(0),
nsim = 0, na.action = na.pass, debug.level = 1,
lambda = 1.0)

```

Arguments

formula	formula that defines the dependent variable as a linear model of independent variables; suppose the dependent variable has name <i>z</i> , for ordinary and use a formula like <i>z~1</i> ; the dependent variable should be NOT transformed.
locations	object of class <i>Spatial</i> , with observations
newdata	<i>Spatial</i> object with prediction/simulation locations; the coordinates should have names as defined in <i>locations</i>
model	variogram model of the TRANSFORMED dependent variable, see vgm , or fit.variogram
nmax	for local kriging: the number of nearest observations that should be used for a kriging prediction or simulation, where nearest is defined in terms of the space of the spatial locations. By default, all observations are used
nmin	for local kriging: if the number of nearest observations within distance <i>maxdist</i> is less than <i>nmin</i> , a missing value will be generated; see <i>maxdist</i>

<code>maxdist</code>	for local kriging: only observations within a distance of <code>maxdist</code> from the prediction location are used for prediction or simulation; if combined with <code>nmax</code> , both criteria apply
<code>block</code>	does not function correctly, afaik
<code>nsim</code>	does not function correctly, afaik
<code>na.action</code>	function determining what should be done with missing values in 'newdata'. The default is to predict 'NA'. Missing values in coordinates and predictors are both dealt with.
<code>lambda</code>	value for the Box-Cox transform
<code>debug.level</code>	debug level, passed to predict.gstat ; use -1 to see progress in percentage, and 0 to suppress all printed information
<code>...</code>	other arguments that will be passed to gstat

Details

Function `krigeTg` uses transGaussian kriging as explained in <http://www.math.umd.edu/~bnk/bak/Plus/kriging.html>.

As it uses the R/`gstat` `krige` function to derive everything, it needs in addition to ordinary kriging on the transformed scale a simple kriging step to find m from the difference between the OK and SK prediction variance, and a kriging/BBLUE estimation step to obtain the estimate of μ .

For further details, see [krige](#) and [predict.gstat](#).

Value

an `SpatialPointsDataFrame` object containing the fields: `m` for the m (Lagrange) parameter for each location; `var1SK.pred` the $c_0 C^{-1}$ correction obtained by `muhat` for the mean estimate at each location; `var1SK.var` the simple kriging variance; `var1.pred` the OK prediction on the transformed scale; `var1.var` the OK kriging variance on the transformed scale; `var1TG.pred` the transGaussian kriging predictor; `var1TG.var` the transGaussian kriging variance, obtained by $\phi'(\hat{\mu}, \lambda)^2 \sigma_{OK}^2$

Author(s)

Edzer Pebesma

References

N.A.C. Cressie, 1993, Statistics for Spatial Data, Wiley.
<http://www.gstat.org/>

See Also

[gstat](#), [predict.gstat](#)

Examples

```

data(meuse)
coordinates(meuse) = ~x+y
data(meuse.grid)
gridded(meuse.grid) = ~x+y
v = vgm(1, "Exp", 300)
x1 = krigeTg(zinc~1,meuse,meuse.grid,v, lambda=1) # no transform
x2 = krige(zinc~1,meuse,meuse.grid,v)
summary(x2$var1.var-x1$var1TG.var)
summary(x2$var1.pred-x1$var1TG.pred)
lambda = -0.25
m = fit.variogram(variogram((zinc^lambda-1)/lambda ~ 1,meuse), vgm(1, "Exp", 300))
x = krigeTg(zinc~1,meuse,meuse.grid,m,lambda=-.25)
spplot(x["var1TG.pred"], col.regions=bpy.colors())
summary(meuse$zinc)
summary(x$var1TG.pred)

```

map.to.lev

*rearrange data frame for plotting with levelplot***Description**

rearrange data frame for plotting with levelplot

Usage

```
map.to.lev(data, xcol = 1, ycol = 2, zcol = c(3, 4), ns = names(data)[zcol])
```

Arguments

data	data frame, e.g. output from krige or predict.gstat
xcol	x-coordinate column number
ycol	y-coordinate column number
zcol	z-coordinate column number range
ns	names of the set of z-columns to be viewed

Value

data frame with the following elements:

x	x-coordinate for each row
y	y-coordinate for each row
z	column vector with each of the elements in columns zcol of data stacked
name	factor; name of each of the stacked z columns

See Also

[image.data.frame](#), [krige](#); for examples see [predict.gstat](#); levelplot in package lattice.

meuse.all

*Meuse river data set - original, full data set***Description**

This data set gives locations and top soil heavy metal concentrations (ppm), along with a number of soil and landscape variables, collected in a flood plain of the river Meuse, near the village Stein. Heavy metal concentrations are bulk sampled from an area of approximately 15 m x 15 m.

Usage

```
data(meuse.all)
```

Format

This data frame contains the following columns:

sample sample number

x a numeric vector; x-coordinate (m) in RDM (Dutch topographical map coordinates)

y a numeric vector; y-coordinate (m) in RDM (Dutch topographical map coordinates)

cadmium topsoil cadmium concentration, ppm.; note that zero cadmium values in the original data set have been shifted to 0.2 (half the lowest non-zero value)

copper topsoil copper concentration, ppm.

lead topsoil lead concentration, ppm.

zinc topsoil zinc concentration, ppm.

elev relative elevation

om organic matter, as percentage

ffreq flooding frequency class

soil soil type

lime lime class

landuse landuse class

dist.m distance to river Meuse (metres), as obtained during the field survey

in.pit logical; indicates whether this is a sample taken in a pit

in.meuse155 logical; indicates whether the sample is part of the `meuse` (i.e., filtered) data set; in addition to the samples in a pit, an sample (139) with outlying zinc content was removed

in.BMcD logical; indicates whether the sample is used as part of the subset of 98 points in the various interpolation examples of Burrough & McDonnell

Note

`sample` refers to original sample number. Eight samples were left out because they were not indicative for the metal content of the soil. They were taken in an old pit. One sample contains an outlying zinc value, which was also discarded for the `meuse` (155) data set.

Author(s)

The actual field data were collected by Ruud van Rijn and Mathieu Rikken; data compiled for R by Edzer Pebesma

References

P.A. Burrough, R.A. McDonnell, 1998. Principles of Geographical Information Systems. Oxford University Press.

<http://www.gstat.org/>

See Also

[meuse.alt](#)

Examples

```
data(meuse.all)
summary(meuse.all)
```

meuse.alt

Meuse river altitude data set

Description

This data set gives a point set with altitudes, digitized from the 1:10,000 topographical map of the Netherlands.

Usage

```
data(meuse.alt)
```

Format

This data frame contains the following columns:

x a numeric vector; x-coordinate (m) in RDM (Dutch topographical map coordinates)

y a numeric vector; y-coordinate (m) in RDM (Dutch topographical map coordinates)

alt altitude in m. above NAP (Dutch zero for sea level)

References

<http://www.gstat.org/>

See Also

[meuse.all](#)

Examples

```
data(meuse.alt)
library(lattice)
xyplot(y~x, meuse.alt, aspect = "iso")
```

ncp.grid

Grid for the NCP, the Dutch part of the North Sea

Description

Gridded data for the NCP, the Dutch part of the North Sea, for a 5 km x 5 km grid; stored as data.frame.

Usage

```
data(ncp.grid)
```

Format

This data frame contains the following columns:

x x-coordinate, UTM31

y y-coordinate, UTM31

depth sea water depth, m

coast distance to coast, m

area identifier for administrative sub-areas

Author(s)

Dutch National Institute for Coastal and Marine Management (RIKZ); data compiled for R by Edzer Pebesma

See Also

[fulmar](#)

Examples

```
data(ncp.grid)
summary(ncp.grid)
```

ossfim

*Kriging standard errors as function of grid spacing and block size***Description**

Calculate, for a given variogram model, ordinary block kriging standard errors as a function of sampling spaces and block sizes

Usage

```
ossfim(spacings = 1:5, block.sizes = 1:5, model, nmax = 25, debug = 0)
```

Arguments

<code>spacings</code>	range of grid (data) spacings to be used
<code>block.sizes</code>	range of block sizes to be used
<code>model</code>	variogram model, output of <code>vgm</code>
<code>nmax</code>	set the kriging neighbourhood size
<code>debug</code>	debug level; set to 32 to see a lot of output

Value

data frame with columns `spacing` (the grid spacing), `block.size` (the block size), and `kriging.se` (block kriging standard error)

Note

The idea is old, simple, but still of value. If you want to map a variable with a given accuracy, you will have to sample it. Suppose the variogram of the variable is known. Given a regular sampling scheme, the kriging standard error decreases when either (i) the data spacing is smaller, or (ii) predictions are made for larger blocks. This function helps quantifying this relationship. `Ossfim` probably refers to “optimal sampling scheme for isarithmic mapping”.

Author(s)

Edzer Pebesma

References

Burrough, P.A., R.A. McDonnell (1999) Principles of Geographical Information Systems. Oxford University Press (e.g., figure 10.11 on page 261)

Burgess, T.M., R. Webster, A.B. McBratney (1981) Optimal interpolation and isarithmic mapping of soil properties. IV Sampling strategy. The journal of soil science 32(4), 643-660.

McBratney, A.B., R. Webster (1981) The design of optimal sampling schemes for local estimation and mapping of regionalized variables: 2 program and examples. Computers and Geosciences 7: 335-365.

read more on a simplified, web-based version on <http://www.gstat.org/ossfim.html>

See Also[krige](#)**Examples**

```
x <- ossfim(1:15,1:15, model = vgm(1,"Exp",15))
library(lattice)
levelplot(kriging.se~spacing+block.size, x,
  main = "Ossfim results, variogram 1 Exp(15)")
# if you wonder about the decrease in the upper left corner of the graph,
# try the above with nmax set to 100, or perhaps 200.
```

oxford

*Oxford soil samples***Description**

Data: 126 soil augerings on a 100 x 100m square grid, with 6 columns and 21 rows. Grid is oriented with long axis North-north-west to South-south-east Origin of grid is South-south-east point, 100m outside grid.

Original data are part of a soil survey carried out by P.A. Burrough in 1967. The survey area is located on the chalk downlands on the Berkshire Downs in Oxfordshire, UK. Three soil profile units were recognised on the shallow Rendzina soils; these are Ia - very shallow, grey calcareous soils less than 40cm deep over chalk; Ct - shallow to moderately deep, grey-brown calcareous soils on calcareous colluvium, and Cr: deep, moderately acid, red-brown clayey soils. These soil profile classes were registered at every augering.

In addition, an independent landscape soil map was made by interpolating soil boundaries between these soil types, using information from the changes in landform. Because the soil varies over short distances, this field mapping caused some soil borings to receive a different classification from the classification based on the point data.

Also registered at each auger point were the site elevation (m), the depth to solid chalk rock (in cm) and the depth to lime in cm. Also, the percent clay content, the Munsell colour components of VALUE and CHROMA , and the lime content of the soil (as tested using HCl) were recorded for the top two soil layers (0-20cm and 20-40cm).

Samples of topsoil taken as a bulk sample within a circle of radius 2.5m around each sample point were used for the laboratory determination of Mg (ppm), OM1 %, CEC as mequ/100g air dry soil, pH, P as ppm and K (ppm).

Usage

```
data(oxford)
```


Format

This data frame contains the following columns:

PROFILE profile number

XCOORD x-coordinate, field, non-projected

YCOORD y-coordinate, field, non-projected

ELEV elevation, m.

PROFCLASS soil class, obtained by classifying the soil profile at the sample site

MAPCLASS soil class, obtained by looking up the site location in the soil map

VAL1 Munsell colour component VALUE, 0-20 cm

CHR1 Munsell colour component CHROMA, 20-40 cm

LIME1 Lime content (tested using HCl), 0-20 cm

VAL2 Munsell colour component VALUE, 0-20 cm

CHR2 Munsell colour component CHROMA, 20-40 cm

LIME2 Lime content (tested using HCl), 20-40 cm

DEPTHCM soil depth, cm

DEP2LIME depth to lime, cm

PCLAY1 percentage clay, 0-20 cm

PCLAY2 percentage clay, 20-40 cm

MG1 Magnesium content (ppm), 0-20 cm

OM1 organic matter (%), 0-20 cm

CEC1 CES as mequ/100g air dry soil, 0-20 cm

PH1 pH, 0-20 cm

PHOS1 Phosphorous, 0-20 cm, ppm

POT1 K (potassium), 0-20 cm, ppm

Note

`oxford.jpg`, in the `gstat` package data directory, shows an image of the soil map for the region

Author(s)

P.A. Burrough; compiled for R by Edzer Pebesma

References

P.A. Burrough, R.A. McDonnell, 1998. Principles of Geographical Information Systems. Oxford University Press.

Examples

```
data(oxford)
summary(oxford)
```

pcb

PCB138 measurements in sediment at the NCP, the Dutch part of the North Sea

Description

This data set gives a point set with altitudes, digitized from the 1:10,000 topographical map of the Netherlands.

Usage

`data(pcb)`

Format

This data frame contains the following columns:

year measurement year

x x-coordinate; UTM31

y y-coordinate; UTM31

coast distance to coast, m.

depth sea water depth, m.

PCB138 PCB-138, measured on the sediment fraction smaller than 63 μ , in $\mu\text{g/kg}$ dry matter;
BUT SEE NOTE BELOW

yf year; as factor

Note

A note of caution: The PCB-138 data are provided only to be able to re-run the analysis done in Pebesma and Duin (2004; see references below). If you want to use these data for comparison with PCB measurements elsewhere, or if you want to compare them to regulation standards, or want to use these data for any other purpose, you should first contact <mailto:basisinfodesk@rikz.rws.minvenw.nl>. The reason for this is that several normalisations were carried out that are not reported here, nor in the paper below.

References

<http://www.gstat.org/>, <http://www.rikz.nl/>

Pebesma, E. J., & Duin, R. N. M. (2005). Spatial patterns of temporal change in North Sea sediment quality on different spatial scales. In P. Renard, H. Demougeot-Renard & R. Froidevaux (Eds.), *Geostatistics for Environmental Applications: Proceedings of the Fifth European Conference on Geostatistics for Environmental Applications* (pp. 367-378): Springer.

See Also

[ncp.grid](#)

Examples

```
data(pcb)
library(lattice)
xyplot(y~x|as.factor(yf), pcb, aspect = "iso")
# demo(pcb)
```

```
plot.gstatVariogram
```

Plot a Sample Variogram

Description

Creates a variogram plot

Usage

```
## S3 method for class 'gstatVariogram'
plot(x, model = NULL, ylim, xlim, xlab = "distance",
     ylab = "semivariance", panel = vgm.panel.xyplot, multipanel = TRUE, plot.numbers =
     scales, ids = x$id, group.id = TRUE, skip, layout, ...)
## S3 method for class 'variogramMap'
plot(x, np = FALSE, skip, threshold, ...)
```

Arguments

x	object of class "gstatVariogram", obtained from the function variogram , possibly containing directional or cross variograms
model	in case of a single variogram: a variogram model, as obtained from vgm or fit.variogram , to be drawn as a line in the variogram plot; in case of a set of variograms and cross variograms: a list with variogram models
ylim	numeric vector of length 2, limits of the y-axis
xlim	numeric vector of length 2, limits of the x-axis
xlab	x-axis label
ylab	y-axis label
panel	panel function
multipanel	logical; if TRUE, directional variograms are plotted in different panels, if FALSE, directional variograms are plotted in the same graph, using color, colored lines and symbols to distinguish them
plot.numbers	logical or numeric; if TRUE, plot number of point pairs next to each plotted semivariance symbol, if FALSE these are omitted. If numeric, TRUE is assumed and the value is passed as the relative distance to be used between symbols and numeric text values (default 0.03).
scales	optional argument that will be passed to <code>xyplot</code> in case of the plotting of variograms and cross variograms; use the value <code>list(relation = "same")</code> if y-axes need to share scales

<code>ids</code>	ids of the data variables and variable pairs
<code>group.id</code>	logical; control for directional multivariate variograms: if TRUE, panels divide direction and colors indicate variables (ids), if FALSE panels divide variables/variable pairs and colors indicate direction
<code>skip</code>	logical; can be used to arrange panels, see <code>xyplot</code>
<code>layout</code>	integer vector; can be used to set panel layout: <code>c(ncol,nrow)</code>
<code>np</code>	logical (only for plotting variogram maps); if TRUE, plot number of point pairs, if FALSE plot semivariances
<code>threshold</code>	semivariogram map values based on fewer point pairs than threshold will not be plotted
<code>...</code>	any arguments that will be passed to the panel plotting functions (such as <code>auto.key</code> in examples below)

Value

returns (or plots) the variogram plot

Note

currently, plotting models and/or point pair numbers is not supported when a variogram is both directional and multivariable; also, three-dimensional directional variograms will probably not be displayed correctly.

Author(s)

Edzer Pebesma

References

<http://www.gstat.org>

See Also

[variogram](#), [fit.variogram](#), [vgm](#) [variogramLine](#),

Examples

```
data(meuse)
coordinates(meuse) = ~x+y
vgm1 <- variogram(log(zinc)~1, meuse)
plot(vgm1)
model.1 <- fit.variogram(vgm1,vgm(1,"Sph",300,1))
plot(vgm1, model=model.1)
plot(vgm1, plot.numbers = TRUE, pch = "+")
vgm2 <- variogram(log(zinc)~1, meuse, alpha=c(0,45,90,135))
plot(vgm2)
# the following demonstrates plotting of directional models:
model.2 <- vgm(.59,"Sph",926,.06,anis=c(0,0.3))
plot(vgm2, model=model.2)
```

```

g = gstat(NULL, "zinc < 200", I(zinc<200)~1, meuse)
g = gstat(g, "zinc < 400", I(zinc<400)~1, meuse)
g = gstat(g, "zinc < 800", I(zinc<800)~1, meuse)
# calculate multivariable, directional variogram:
v = variogram(g, alpha=c(0,45,90,135))
plot(v, group.id = FALSE, auto.key = TRUE) # id and id pairs panels
plot(v, group.id = TRUE, auto.key = TRUE)  # direction panels

# variogram maps:
plot(variogram(g, cutoff=1000, width=100, map=TRUE),
     main = "(cross) semivariance maps")
plot(variogram(g, cutoff=1000, width=100, map=TRUE), np=TRUE,
     main = "number of point pairs")

```

plot.pointPairs	<i>Plot a point pairs, identified from a variogram cloud</i>
-----------------	--

Description

Plot a point pairs, identified from a variogram cloud

Usage

```

## S3 method for class 'pointPairs'
plot(x, data, xcol = data$x, ycol = data$y, xlab = "x coordinate",
     ylab = "y coordinate", col.line = 2, line.pch = 0, main = "selected point pairs", .

```

Arguments

x	object of class "pointPairs", obtained from the function plot.variogramCloud , containing point pair indices
data	data frame to which the indices refer (from which the variogram cloud was calculated)
xcol	numeric vector with x-coordinates of data
ycol	numeric vector with y-coordinates of data
xlab	x-axis label
ylab	y-axis label
col.line	color for lines connecting points
line.pch	if non-zero, symbols are also plotted at the middle of line segments, to mark lines too short to be visible on the plot; the color used is col.line; the value passed to this argument will be used as plotting symbol (pch)
main	title of plot
...	arguments, further passed to xyplot

Value

plots the data locations, with lines connecting the point pairs identified (and referred to by indices in) `x`

Author(s)

Edzer Pebesma

References

<http://www.gstat.org>

See Also

[plot.variogramCloud](#)

Examples

```
### The following requires interaction, and is therefore outcommented
#data(meuse)
#coordinates(meuse) = ~x+y
#vgml <- variogram(log(zinc)~1, meuse, cloud = TRUE)
#pp <- plot(vgml, id = TRUE)
### Identify the point pairs
#plot(pp, data = meuse) # meuse has x and y as coordinates
```

```
plot.variogramCloud
```

Plot and Identify Data Pairs on Sample Variogram Cloud

Description

Plot a sample variogram cloud, possibly with identification of individual point pairs

Usage

```
## S3 method for class 'variogramCloud'
plot(x, identify = FALSE, digitize = FALSE, xlim, ylim, xlab, ylab,
keep = FALSE, ...)
```

Arguments

<code>x</code>	object of class <code>variogramCloud</code>
<code>identify</code>	logical; if <code>TRUE</code> , the plot allows identification of a series of individual point pairs that correspond to individual variogram cloud points (use left mouse button to select; right mouse button ends)
<code>digitize</code>	logical; if <code>TRUE</code> , select point pairs by digitizing a region with the mouse (left mouse button adds a point, right mouse button ends)

xlim	limits of x-axis
ylim	limits of y-axis
xlab	x axis label
ylab	y axis label
keep	logical; if TRUE and identify is TRUE, the labels identified and their position are kept and glued to object x, which is returned. Subsequent calls to plot this object will now have the labels shown, e.g. to plot to hardcopy
...	parameters that are passed through to plot.gstatVariogram (in case of identify = FALSE) or to plot (in case of identify = TRUE)

Value

If identify or digitize is TRUE, a data frame of class pointPairs with in its rows the point pairs identified (pairs of row numbers in the original data set); if identify is F, a plot of the variogram cloud, which uses [plot.gstatVariogram](#)

If in addition to identify, keep is also TRUE, an object of class variogramCloud is returned, having attached to it attributes "sel" and "text", which will be used in subsequent calls to plot.variogramCloud with identify set to FALSE, to plot the text previously identified.

If in addition to digitize, keep is also TRUE, an object of class variogramCloud is returned, having attached to it attribute "poly", which will be used in subsequent calls to plot.variogramCloud with digitize set to FALSE, to plot the digitized line.

In both of the keep = TRUE cases, the attribute ppairs of class pointPairs is present, containing the point pairs identified.

Author(s)

Edzer Pebesma

References

<http://www.gstat.org/>

See Also

[variogram](#), [plot.gstatVariogram](#), [plot.pointPairs](#), [identify](#), [locator](#)

Examples

```
data(meuse)
coordinates(meuse) = ~x+y
plot(variogram(log(zinc)~1, meuse, cloud=TRUE))
## commands that require interaction:
# x <- variogram(log(zinc)~1, loc=~x+y, data=meuse, cloud=TRUE)
# plot(plot(x, identify = TRUE), meuse)
# plot(plot(x, digitize = TRUE), meuse)
```

Description

The function provides the following prediction methods: simple, ordinary, and universal kriging, simple, ordinary, and universal cokriging, point- or block-kriging, and conditional simulation equivalents for each of the kriging methods.

Usage

```
predict.gstat(object, newdata, block = numeric(0), nsim = 0,
  indicators = FALSE, BLUE = FALSE, debug.level = 1, mask,
  na.action = na.pass, sps.args = list(n = 500, type = "regular",
  offset = c(.5, .5)), ...)
```

Arguments

object	object of class <code>gstat</code> , see gstat and krige
newdata	data frame with prediction/simulation locations; should contain columns with the independent variables (if present) and the coordinates with names as defined in <code>locations</code>
block	block size; a vector with 1, 2 or 3 values containing the size of a rectangular in x-, y- and z-dimension respectively (0 if not set), or a data frame with 1, 2 or 3 columns, containing the points that discretize the block in the x-, y- and z-dimension to define irregular blocks relative to (0,0) or (0,0,0)—see also the details section below. By default, predictions or simulations refer to the support of the data values.
nsim	integer; if set to a non-zero value, conditional simulation is used instead of kriging interpolation. For this, sequential Gaussian or indicator simulation is used (depending on the value of <code>indicators</code>), following a single random path through the data.
indicators	logical; only relevant if <code>nsim</code> is non-zero; if TRUE, use indicator simulation, else use Gaussian simulation
BLUE	logical; if TRUE return the BLUE trend estimates only, if FALSE return the BLUP predictions (kriging)
debug.level	integer; set <code>gstat</code> internal debug level, see below for useful values. If set to -1 (or any negative value), a progress counter is printed
mask	not supported anymore – use <code>na.action</code> ; logical or numerical vector; pattern with valid values in <code>newdata</code> (marked as TRUE, non-zero, or non-NA); if mask is specified, the returned data frame will have the same number and order of rows in <code>newdata</code> , and masked rows will be filled with NA's.

<code>na.action</code>	function determining what should be done with missing values in 'newdata'. The default is to predict 'NA'. Missing values in coordinates and predictors are both dealt with.
<code>sps.args</code>	when newdata is of class <code>SpatialPolygons</code> or <code>SpatialPolygonsDataFrame</code> this argument list gets passed to <code>spsample</code> in package <code>sp</code> to control the discretizing of polygons
<code>...</code>	ignored (but necessary for the S3 generic/method consistency)

Details

When a non-stationary (i.e., non-constant) mean is used, both for simulation and prediction purposes the variogram model defined should be that of the residual process, not that of the raw observations.

For irregular block kriging, coordinates should discretize the area relative to (0), (0,0) or (0,0,0); the coordinates in newdata should give the centroids around which the block should be located. So, suppose the block is discretized by points (3,3) (3,5) (5,5) and (5,3), we should pass point (4,4) in newdata and pass points (-1,-1) (-1,1) (1,1) (1,-1) to the block argument. Although passing the uncentered block and (0,0) as newdata may work for global neighbourhoods, neighbourhood selection is always done relative to the centroid values in newdata.

If newdata is of class `SpatialPolygons` or `SpatialPolygonsDataFrame` (see package `sp`), then the block average for each of the polygons or polygon sets is calculated, using `spsample` to discretize the polygon(s). `sps.args` controls the parameters used for `spsample`. The "location" with respect to which neighbourhood selection is done is for each polygon the `SpatialPolygons` polygon label point; if you use local neighbourhoods you should check out where these points are—this may be well outside the ring itself.

The algorithm used by `gstat` for simulation random fields is the sequential simulation algorithm. This algorithm scales well to large or very large fields (e.g., more than 10^6 nodes). Its power lies in using only data and simulated values in a local neighbourhood to approximate the conditional distribution at that location, see `nmax` in [krige](#) and [gstat](#). The larger `nmax`, the better the approximation, the smaller `nmax`, the faster the simulation process. For selecting the nearest `nmax` data or previously simulated points, `gstat` uses a bucket PR quadtree neighbourhood search algorithm; see the reference below.

For sequential Gaussian or indicator simulations, a random path through the simulation locations is taken, which is usually done for sequential simulations. The reason for this is that the local approximation of the conditional distribution, using only the `nmax` nearest observed (or simulated) values may cause spurious correlations when a regular path would be followed. Following a single path through the locations, `gstat` reuses the expensive results (neighbourhood selection and solution to the kriging equations) for each of the subsequent simulations when multiple realisations are requested. You may expect a considerable speed gain in simulating 1000 fields in a single call to [predict.gstat](#), compared to 1000 calls, each for simulating a single field.

The random number generator used for generating simulations is the native random number generator of the environment (R, S); fixing randomness by setting the random number seed with `set.seed()` works.

When mean coefficient are not supplied, they are generated as well from their conditional distribution (assuming multivariate normal, using the generalized least squares BLUE estimate and its estimation covariance); for a reference to the algorithm used see Abrahamsen and Benth, *Math. Geol.* 33(6), page 742 and leave out all constraints.

Memory requirements for sequential simulation: let n be the product of the number of variables, the number of simulation locations, and the number of simulations required in a single call. the `gstat` C function `gstat_predict` requires a table of size $n * 12$ bytes to pass the simulations back to R, before it can free $n * 4$ bytes. Hopefully, R does not have to duplicate the remaining $n * 8$ bytes when the coordinates are added as columns, and when the resulting matrix is coerced to a `data.frame`.

Useful values for `debug.level`: 0: suppress any output except warning and error messages; 1: normal output (default): short data report, program action and mode, program progress in %, total execution time; 2: print the value of all global variables, all files read and written, and include source file name and line number in error messages; 4: print OLS and WLS fit diagnostics; 8: print all data after reading them; 16: print the neighbourhood selection for each prediction location; 32: print (generalised) covariance matrices, design matrices, solutions, kriging weights, etc.; 64: print variogram fit diagnostics (number of iterations and variogram model in each iteration step) and order relation violations (indicator kriging values before and after order relation correction); 512: print block (or area) discretization data for each prediction location. To combine settings, sum their respective values. Negative values for `debug.level` are equal to positive, but cause the progress counter to work.

For data with longitude/latitude coordinates (checked by `is.projected`), `gstat` uses great circle distances in km to compute spatial distances. The user should make sure that the semivariogram model used is positive definite on a sphere.

Value

a data frame containing the coordinates of `newdata`, and columns of prediction and prediction variance (in case of kriging) or the columns of the conditional Gaussian or indicator simulations

Author(s)

Edzer Pebesma

References

N.A.C. Cressie, 1993, *Statistics for Spatial Data*, Wiley.

<http://www.gstat.org/>

Pebesma, E.J., 2004. Multivariable geostatistics in S: the `gstat` package. *Computers & Geosciences*, 30: 683-691.

For bucket PR quadrees, excellent demos are found at <http://www.cs.umd.edu/~brabec/quadtree/index.html>

See Also

[gstat](#), [krige](#)

Examples

```
# generate 5 conditional simulations
data(meuse)
coordinates(meuse) = ~x+y
```

```

v <- variogram(log(zinc)~1, meuse)
m <- fit.variogram(v, vgm(1, "Sph", 300, 1))
plot(v, model = m)
set.seed(131)
data(meuse.grid)
gridded(meuse.grid) = ~x+y
sim <- krige(formula = log(zinc)~1, meuse, meuse.grid, model = m,
nmax = 15, beta = 5.9, nsim = 5)
# show all 5 simulation
spplot(sim)

# calculate generalised least squares residuals w.r.t. constant trend:
g <- gstat(NULL, "log.zinc", log(zinc)~1, meuse, model = m)
blue0 <- predict(g, newdata = meuse, BLUE = TRUE)
blue0$blue.res <- log(meuse$zinc) - blue0$log.zinc.pred
bubble(blue0, zcol = "blue.res", main = "GLS residuals w.r.t. constant")

# calculate generalised least squares residuals w.r.t. linear trend:
m <- fit.variogram(variogram(log(zinc)~sqrt(dist.m), meuse),
vgm(1, "Sph", 300, 1))
g <- gstat(NULL, "log.zinc", log(zinc)~sqrt(dist.m), meuse, model = m)
blue1 <- predict(g, meuse, BLUE = TRUE)
blue1$blue.res <- log(meuse$zinc) - blue1$log.zinc.pred
bubble(blue1, zcol = "blue.res",
main = "GLS residuals w.r.t. linear trend")

# unconditional simulation on a 100 x 100 grid
xy <- expand.grid(1:100, 1:100)
names(xy) <- c("x", "y")
g.dummy <- gstat(formula = z~1, locations = ~x+y, dummy = TRUE, beta = 0,
model = vgm(1, "Exp", 15), nmax = 20)
yy <- predict(g.dummy, newdata = xy, nsim = 4)
# show one realisation:
gridded(yy) = ~x+y
spplot(yy[1])
# show all four:
spplot(yy)

```

show.vgms

Plot Variogram Model Functions

Description

Creates a trellis plot for a range of variogram models, possibly with nugget; and optionally a set of Matern models with varying smoothness.

Usage

```
show.vgms(min = 1e-12 * max, max = 3, n = 50, sill = 1, range = 1,
```

```
models = as.character(vgm()$short[c(1:17)]), nugget = 0, kappa.range = 0.5,
plot = TRUE, ...)
```

Arguments

<code>min</code>	numeric; start distance value for semivariance calculation beyond the first point at exactly zero
<code>max</code>	numeric; maximum distance for semivariance calculation and plotting
<code>n</code>	integer; number of points to calculate distance values
<code>sill</code>	numeric; (partial) sill of the variogram model
<code>range</code>	numeric; range of the variogram model
<code>models</code>	character; variogram models to be plotted
<code>nugget</code>	numeric; nugget component for variogram models
<code>kappa.range</code>	numeric; if this is a vector with more than one element, only a range of Matern models is plotted with these kappa values
<code>plot</code>	logical; if TRUE, a plot is returned with the models specified; if FALSE, the data prepared for this plot is returned
<code>...</code>	passed on to the call to <code>xyplot</code>

Value

returns a (Trellis) plot of the variogram models requested; see examples. I do currently have strong doubts about the “correctness” of the “Hol” model. The “Spl” model does seem to need a very large range value (larger than the study area?) to be of some value.

If `plot` is FALSE, a data frame with the data prepared to plot is being returned.

Note

the `min` argument is supplied because the variogram function may be discontinuous at distance zero, surely when a positive nugget is present.

Author(s)

Edzer Pebesma

References

<http://www.gstat.org>

See Also

[vgm](#), [variogramLine](#),

Examples

```
show.vgms()
show.vgms(models = c("Exp", "Mat", "Gau"), nugget = 0.1)
# show a set of Matern models with different smoothness:
show.vgms(kappa.range = c(.1, .2, .5, 1, 2, 5, 10), max = 10)
# show a set of Exponential class models with different shape parameter:
show.vgms(kappa.range = c(.05, .1, .2, .5, 1, 1.5, 1.8, 1.9, 2), models = "Exc", max = 10)
# show a set of models with different shape parameter of M. Stein's representation of the Ma
show.vgms(kappa.range = c(.01, .02, .05, .1, .2, .5, 1, 2, 5, 1000), models = "Ste", max = 2
```

sic2004

Spatial Interpolation Comparison 2004 data set: Natural Ambient Radioactivity

Description

The text below is copied from <http://www.ai-geostats.org/events/sic2004/index.htm>, subsection Data.

The variable used in the SIC 2004 exercise is natural ambient radioactivity measured in Germany. The data, provided kindly by the German Federal Office for Radiation Protection (BfS), are gamma dose rates reported by means of the national automatic monitoring network (IMIS).

In the frame of SIC2004, a rectangular area was used to select 1008 monitoring stations (from a total of around 2000 stations). For these 1008 stations, 11 days of measurements have been randomly selected during the last 12 months and the average daily dose rates calculated for each day. Hence, we ended up having 11 data sets.

Prior information (sic.train): 10 data sets of 200 points that are identical for what concerns the locations of the monitoring stations have been prepared. These locations have been randomly selected (see Figure 1). These data sets differ only by their Z values since each set corresponds to 1 day of measurement made during the last 14 months. No information will be provided on the date of measurement. These 10 data sets (10 days of measurements) can be used as prior information to tune the parameters of the mapping algorithms. No other information will be provided about these sets. Participants are free of course to gather more information about the variable in the literature and so on.

The 200 monitoring stations above were randomly taken from a larger set of 1008 stations. The remaining 808 monitoring stations have a topology given in sic.pred. Participants to SIC2004 will have to estimate the values of the variable taken at these 808 locations.

The SIC2004 data (sic.val, variable dayx): The exercise consists in using 200 measurements made on a 11th day (THE data of the exercise) to estimate the values observed at the remaining 808 locations (hence the question marks as symbols in the maps shown in Figure 3). These measurements will be provided only during two weeks (15th of September until 1st of October 2004) on a web page restricted to the participants. The true values observed at these 808 locations will be released only at the end of the exercise to allow participants to write their manuscripts (sic.test, variables dayx and joker).

In addition, a joker data set was released (sic.val, variable joker), which contains an anomaly. The anomaly was generated by a simulation model, and does not represent measured levels.

Usage

```
data(sic2004) #
```

Format

The data frames contain the following columns:

record this integer value is the number (unique value) of the monitoring station chosen by us.
x X-coordinate of the monitoring station indicated in meters
y Y-coordinate of the monitoring station indicated in meters
day01 mean gamma dose rate measured during 24 hours, at day01. Units are nanoSieverts/hour
day02 same, for day 02
day03 ...
day04 ...
day05 ...
day06 ...
day07 ...
day08 ...
day09 ...
day10 ...
dayx the data observed at the 11-th day
joker the joker data set, containing an anomaly not present in the training data

Note

the data set sic.grid provides a set of points on a regular grid (almost 10000 points) covering the area; this is convenient for interpolation; see the function `makegrid` in package `sp`.

The coordinates have been projected around a point located in the South West of Germany. Hence, a few coordinates have negative values as can be guessed from the Figures below.

Author(s)

Data: the German Federal Office for Radiation Protection (BfS), <http://www.bfs.de/>, data provided by Gregoire Dubois, R compilation by Edzer Pebesma.

References

<http://www.ai-geostats.org/>, http://www.ai-geostats.org/resources/sic2004_data.htm, <http://www.ai-geostats.org/events/sic2004/index.htm>

Examples

```
data(sic2004)
# FIGURE 1. Locations of the 200 monitoring stations for the 11 data sets.
# The values taken by the variable are known.
plot(y~x,sic.train,pch=1,col="red", asp=1)

# FIGURE 2. Locations of the 808 remaining monitoring stations at which
# the values of the variable must be estimated.
plot(y~x,sic.pred,pch="?", asp=1, cex=.8) # Figure 2

# FIGURE 3. Locations of the 1008 monitoring stations (exhaustive data sets).
# Red circles are used to estimate values located at the questions marks
plot(y~x,sic.train,pch=1,col="red", asp=1)
points(y~x, sic.pred, pch="?", cex=.8)
```

 sic97

Spatial Interpolation Comparison 1997 data set: Swiss Rainfall

Description

The text below is copied from the data item at <http://www.ai-geostats.org/>

Usage

```
data(sic97) #
```

Format

The data frames contain the following columns:

ID this integer value is the number (unique value) of the monitoring station

rainfall rainfall amount, in 10th of mm

Note

See the pdf that accompanies the original file for a description of the data. The .dxf file with the Swiss border is not included here.

Author(s)

Gregoire Dubois and others.

References

<http://www.ai-geostats.org/>,

Examples

```
data(sic97)
image(demstd)
points(sic_full, pch=1)
points(sic_obs, pch=3)
```

```
spplot.vcov
```

Plot map matrix of prediction error variances and covariances

Description

Plot map matrix of prediction error variances and covariances

Usage

```
spplot.vcov(x, ...)
```

Arguments

<code>x</code>	Object of class <code>SpatialPixelsDataFrame</code> or <code>SpatialGridDataFrame</code> , resulting from a kriging call with multiple variables (cokriging)
<code>...</code>	remaining arguments passed to <code>spplot</code>

Value

The plotted object, of class `trellis`; see `spplot` in package **sp**.

Author(s)

Edzer Pebesma

```
tull
```

Südliche Tullnerfeld data set

Description

The Südliche Tullnerfeld is a part of the Danube river basin in central Lower Austria and due to its homogeneous aquifer well suited for a model-oriented geostatistical analysis. It contains 36 official water quality measurement stations, which are irregularly spread over the region.

Usage

```
data(tull)
```


Format

The data frames contain the following columns:

x X location in meter

y Y location in meter

S411 Station name

S429 Station name

S849 Station name

S854 Station name

S1502 Station name

S1584 Station name

S1591 Station name

S2046 Station name

S2047 Station name

S2048 Station name

S2049 Station name

S2051 Station name

S2052 Station name

S2053 Station name

S2054 Station name

S2055 Station name

S2057 Station name

S2058 Station name

S2059 Station name

S2060 Station name

S2061 Station name

S2062 Station name

S2063 Station name

S2064 Station name

S2065 Station name

S2066 Station name

S2067 Station name

S2070 Station name

S2071 Station name

S2072 Station name

S2128 Station name

S5319 Station name

S5320 Station name

S5321 Station name

S5322 Station name

S5323 Station name

Note

This data set was obtained on May 6, 2008 from http://www.ifas.jku.at/e5361/index_ger.html. The author of the book that uses it is found at: http://www.ifas.jku.at/e2571/e2604/index_ger.html

References

Werner G. Müller, Collecting Spatial Data, 3rd edition. Springer Verlag, Heidelberg, 2007

Examples

```
data(tull)

# TULLNREG = read.csv("TULLNREG.csv")

# I modified tulln36des.csv, such that the first line only contained: x,y
# resulting in row.names that reflect the station ID, as in
# tull36 = read.csv("tulln36des.csv")

# Chlorid92 was read & converted by:
#Chlorid92=read.csv("Chlorid92.csv")
#Chlorid92$Datum = as.POSIXct(strptime(Chlorid92$Datum, "%d.%m.%y"))

summary(tull36)
summary(TULLNREG)
summary(Chlorid92)

# stack & join data to x,y,Date,Chloride form:
cl.st = stack(Chlorid92[-1])
names(cl.st) = c("Chloride", "Station")
cl.st$Date = rep(Chlorid92$Datum, length(names(Chlorid92))-1)
cl.st$x = tull36[match(cl.st[, "Station"], row.names(tull36)), "x"]
cl.st$y = tull36[match(cl.st[, "Station"], row.names(tull36)), "y"]
# library(lattice)
# xyplot(Chloride~Date|Station, cl.st)
# xyplot(y~x|Date, cl.st, asp="iso", layout=c(16,11))
summary(cl.st)
plot(TULLNREG, pch=3, asp=1)
points(y~x, cl.st, add=TRUE, pch=16)
```

variogram

Calculate Sample or Residual Variogram or Variogram Cloud

Description

Calculates the sample variogram from data, or in case of a linear model is given, for the residuals, with options for directional, robust, and pooled variogram, and for irregular distance intervals.

Usage

```
variogram(object, ...)
```

Usage

```
## S3 method for class 'formula'
variogram(object, ...)
## S3 method for class 'gstat'
variogram(formula, locations, data, ...)
## Default S3 method:
variogram(y, locations, X, cutoff, width = cutoff/15, alpha =
0, beta = 0, tol.hor = 90/length(alpha), tol.ver =
90/length(beta), cressie = FALSE, dX = numeric(0), boundaries =
numeric(0), cloud = FALSE, trend.beta = NULL, debug.level = 1,
cross = TRUE, grid, map = FALSE, g = NULL, ..., projected = TRUE, lambda = 1.0)
## S3 method for class 'line'
variogram(..., deprecate = TRUE)
## S3 method for class 'gstatVariogram'
print(v, ...)
## S3 method for class 'variogramCloud'
print(v, ...)
```

Arguments

object	object of class <code>gstat</code> ; in this form, direct and cross (residual) variograms are calculated for all variables and variable pairs defined in <code>object</code>
formula	formula defining the response vector and (possible) regressors, in case of absence of regressors, use e.g. <code>z~1</code>
data	data frame where the names in formula are to be found
locations	spatial data locations. For <code>variogram.formula</code> : a formula with only the coordinate variables in the right hand (explanatory variable) side e.g. <code>~x+y</code> ; see examples. For <code>variogram.default</code> : list with coordinate matrices, each with the number of rows matching that of corresponding vectors in <code>y</code> ; the number of columns should match the number of spatial dimensions spanned by the data (1 (x), 2 (x,y) or 3 (x,y,z)).
...	any other arguments that will be passed to <code>variogram.default</code> (ignored)
y	list with for each variable the vector with responses
X	(optional) list with for each variable the matrix with regressors/covariates; the number of rows should match that of the corresponding element in <code>y</code> , the number of columns equals the number of regressors (including intercept)
cutoff	spatial separation distance up to which point pairs are included in semivariance estimates; as a default, the length of the diagonal of the box spanning the data is divided by three.
width	the width of subsequent distance intervals into which data point pairs are grouped for semivariance estimates

<code>alpha</code>	direction in plane (x,y), in positive degrees clockwise from positive y (North): $\alpha=0$ for direction North (increasing y), $\alpha=90$ for direction East (increasing x); optional a vector of directions in (x,y)
<code>beta</code>	direction in z, in positive degrees up from the (x,y) plane; optional a vector of directions
<code>tol.hor</code>	horizontal tolerance angle in degrees
<code>tol.ver</code>	vertical tolerance angle in degrees
<code>cressie</code>	logical; if TRUE, use Cressie's robust variogram estimate; if FALSE use the classical method of moments variogram estimate
<code>dX</code>	include a pair of data points $y(s_1), y(s_2)$ taken at locations s_1 and s_2 for sample variogram calculation only when $\ x(s_1) - x(s_2)\ < dX$ with and $x(s_i)$ the vector with regressors at location s_i , and $\ \cdot\ $ the 2-norm. This allows pooled estimation of within-strata variograms (use a factor variable as regressor, and $dX=0.5$), or variograms of (near-)replicates in a linear model (addressing point pairs having similar values for regressors variables)
<code>boundaries</code>	numerical vector with distance interval boundaries; values should be strictly increasing
<code>cloud</code>	logical; if TRUE, calculate the semivariogram cloud
<code>trend.beta</code>	vector with trend coefficients, in case they are known. By default, trend coefficients are estimated from the data.
<code>debug.level</code>	integer; set gstat internal debug level
<code>cross</code>	logical; if FALSE, no cross variograms are calculated when object is of class <code>gstat</code> and has more than one variable
<code>v</code>	object of class <code>variogram</code> or <code>variogramCloud</code> to be printed
<code>grid</code>	grid parameters, if data are gridded (not to be called directly; this is filled automatically)
<code>map</code>	logical; if TRUE, and <code>cutoff</code> and <code>width</code> are given, a variogram map is returned. This requires package <code>sp</code> . Alternatively, a map can be passed, of class <code>SpatialDataFrameGrid</code> (see <code>sp</code> docs)
<code>deprecate</code>	logical; if TRUE, a message will be printed to say that this function is deprecated. Function <code>variogram.line</code> will be deprecated in favour of the identical <code>variogramLine</code>
<code>g</code>	NULL or object of class <code>gstat</code> ; may be used to pass settable parameters and/or variograms; see example
<code>projected</code>	logical; if FALSE, data are assumed to be unprojected, meaning decimal longitude/latitude. For projected data, Euclidian distances are computed, for unprojected great circle distances (km). In <code>variogram.formula</code> or <code>variogram.gstat</code> , for data deriving from class <code>Spatial</code> , projection is detected automatically using <code>is.projected</code>
<code>lambda</code>	test feature; not working (yet)

Value

If `map` is `TRUE` (or a map is passed), a grid map is returned containing the (cross) variogram map(s). See package `sp`.

In other cases, an object of class `"gstatVariogram"` with the following fields:

<code>np</code>	the number of point pairs for this estimate; in case of a <code>variogramCloud</code> see below
<code>dist</code>	the average distance of all point pairs considered for this estimate
<code>gamma</code>	the actual sample variogram estimate
<code>dir.hor</code>	the horizontal direction
<code>dir.ver</code>	the vertical direction
<code>id</code>	the combined id pair

If `cloud` is `TRUE`: an object of class `variogramCloud`, with the field `np` encoding the numbers of the point pair that contributed to a variogram cloud estimate, as follows. The first point is found by `1 +` the integer division of `np` by the `.BigInt` attribute of the returned object, the second point by `1 +` the remainder of that division. [as.data.frame.variogramCloud](#) returns no `np` field, but does the decoding into:

<code>left</code>	for <code>variogramCloud</code> : data id (row number) of one of the data pair
<code>right</code>	for <code>variogramCloud</code> : data id (row number) of the other data in the pair

In the past, `gstat` returned an object of class `"variogram"`; however, this resulted in confusions for users of the package `geoR`: the `geoR` `variog` function also returns objects of class `"variogram"`, incompatible to those returned by this function. That's why I changed the class name.

Note

`variogram.line` is **DEPRECATED**; it is and was never meant as a variogram method, but works automatically as such by the R dispatch system. Use `variogramLine` instead.

Author(s)

Edzer Pebesma

References

Cressie, N.A.C., 1993, Statistics for Spatial Data, Wiley.

<http://www.gstat.org/>

Pebesma, E.J., 2004. Multivariable geostatistics in S: the `gstat` package. *Computers & Geosciences*, 30: 683-691.

See Also

[print.gstatVariogram](#), [plot.gstatVariogram](#), [plot.variogramCloud](#); for variogram models: [vgm](#), to fit a variogram model to a sample variogram: [fit.variogram](#)

Examples

```
data(meuse)
# no trend:
coordinates(meuse) = ~x+y
variogram(log(zinc)~1, meuse)
# residual variogram w.r.t. a linear trend:
variogram(log(zinc)~x+y, meuse)
# directional variogram:
variogram(log(zinc)~x+y, meuse, alpha=c(0,45,90,135))

# GLS residual variogram:
v = variogram(log(zinc)~x+y, meuse)
v.fit = fit.variogram(v, vgm(1, "Sph", 700, 1))
v.fit
set = list(gls=1)
v
g = gstat(NULL, "log-zinc", log(zinc)~x+y, meuse, model=v.fit, set = set)
variogram(g)

if (require(rgdal)) {
  proj4string(meuse) = CRS("+init=epsg:28992")
  meuse.ll = spTransform(meuse, CRS("+proj=longlat"))
# variogram of unprojected data, using great-circle distances, returning km as units
variogram(log(zinc) ~ 1, meuse.ll)
}
```

variogramLine

Semivariance Values For a Given Variogram Model

Description

Generates a semivariance values given a variogram model

Usage

```
variogramLine(object, maxdist, n = 200, min = 1.0e-6 * maxdist,
  dir = c(1,0,0), covariance = FALSE, ..., dist_vector, debug.level = 0)
```

Arguments

object	variogram model for which we want semivariance function values
maxdist	maximum distance for which we want semivariance values
n	number of points
min	minimum distance; a value slightly larger than zero is usually used to avoid the discontinuity at distance zero if a nugget component is present
dir	direction vector: unit length vector pointing the direction in x (East-West), y (North-South) and z (Up-Down)

covariance	logical; if TRUE return covariance values, otherwise return semivariance values
...	ignored
dist_vector	numeric vector or matrix with distance values
debug.level	gstat internal debug level

Value

a data frame of dimension (n x 2), with columns distance and gamma (semivariances or covariances), or in case `dist_vector` is a matrix, a conforming matrix with semivariance/covariance values is returned.

Note

`variogramLine` is used to generate data for plotting a variogram model.

Author(s)

Edzer Pebesma

See Also

[plot.gstatVariogram](#)

Examples

```
variogramLine(vgm(5, "Exp", 10, 5), 10, 10)
# anisotropic variogram, plotted in E-W direction:
variogramLine(vgm(1, "Sph", 10, anis=c(0,0.5)), 10, 10)
# anisotropic variogram, plotted in N-S direction:
variogramLine(vgm(1, "Sph", 10, anis=c(0,0.5)), 10, 10, dir=c(0,1,0))
variogramLine(vgm(1, "Sph", 10, anis=c(0,0.5)), dir=c(0,1,0), dist_vector = 0.5)
variogramLine(vgm(1, "Sph", 10, anis=c(0,0.5)), dir=c(0,1,0), dist_vector = c(0, 0.5, 0.75))
```

vgm

Generate, or Add to Variogram Model

Description

Generates a variogram model, or adds to an existing model. `print.variogramModel` prints the essence of a variogram model.

Usage

```
vgm(psil1, model, range, nugget, add.to, anis, kappa = 0.5, ..., covtable)
## S3 method for class 'variogramModel'
print(x, ...)
as.vgm.variomodel(m)
```

Arguments

<code>psill</code>	(partial) sill of the variogram model component
<code>model</code>	model type, e.g. "Exp", "Sph", "Gau", "Mat". Calling <code>vgm()</code> without a model argument returns a <code>data.frame</code> with available models.
<code>range</code>	range of the variogram model component; in case of anisotropy: major range
<code>kappa</code>	smoothness parameter for the Matern class of variogram models
<code>nugget</code>	nugget component of the variogram (this basically adds a nugget component to the model)
<code>add.to</code>	the variogram model to which we want to add a component (structure)
<code>anis</code>	anisotropy parameters: see notes below
<code>x</code>	a variogram model to print
<code>...</code>	arguments that will be passed to <code>print</code> , e.g. <code>digits</code> (see examples)
<code>covtable</code>	if model is <code>Tab</code> , instead of model parameters a one-dimensional covariance table can be passed here. See <code>covtable.R</code> in tests directory, and example below.
<code>m</code>	object of class <code>variomodel</code> , see geoR

Value

an object of class `variogramModel`, which extends `data.frame`.

When called without a model argument, a `data.frame` with available models is returned, having two columns: short (abbreviated names, to be used as model argument: "Exp", "Sph" etc) and long (with some description).

`as.vgm.variomodel` tries to convert an object of class `variomodel` (**geoR**) to `vgm`.

Note

Geometric anisotropy can be modelled for each individual simple model by giving two or five anisotropy parameters, two for two-dimensional and five for three-dimensional data. In any case, the range defined is the range in the direction of the strongest correlation, or the major range. Anisotropy parameters define which direction this is (the main axis), and how much shorter the range is in (the) direction(s) perpendicular to this main axis.

In two dimensions, two parameters define an anisotropy ellipse, say `anis = c(30, 0.5)`. The first parameter, 30, refers to the main axis direction: it is the angle for the principal direction of continuity (measured in degrees, clockwise from positive Y, i.e. North). The second parameter, 0.5, is the anisotropy ratio, the ratio of the minor range to the major range (a value between 0 and 1). So, in our example, if the range in the major direction (North-East) is 100, the range in the minor direction (South-East) is $0.5 \times 100 = 50$.

In three dimensions, five values should be given in the form `anis = c(p, q, r, s, t)`. Now, `p` is the angle for the principal direction of continuity (measured in degrees, clockwise from Y, in direction of X), `q` is the dip angle for the principal direction of continuity (measured in positive degrees up from horizontal), `r` is the third rotation angle to rotate the two minor directions around the principal direction defined by `p` and `q`. A positive angle acts counter-clockwise while looking in the principal direction. Anisotropy ratios `s` and `t` are the ratios between the major range and each of the two minor ranges. The anisotropy code was taken from **GSLIB**. Note that in

http://www.gslib.com/sec_gb.html it is reported that this code has a bug. Quoting from this site: “The third angle in all GSLIB programs operates in the opposite direction than specified in the GSLIB book. Explanation - The book says (pp27) the angle is measured clockwise when looking toward the origin (from the positive principal direction), but it should be counter-clockwise. This is a documentation error. Although rarely used, the correct specification of the third angle is critical if used.”

(Note that `anis = c(p, s)` is equivalent to `anis = c(p, 0, 0, s, 1)`.)

The implementation in `gstat` for 2D and 3D anisotropy was taken from the `gslib` (probably 1992) code. I have seen a paper where it is argued that the 3D anisotropy code implemented in `gslib` (and so in `gstat`) is in error, but I have not corrected anything afterwards.

Author(s)

Edzer Pebesma

References

<http://www.gstat.org/>

Pebesma, E.J., 2004. Multivariable geostatistics in S: the `gstat` package. *Computers & Geosciences*, 30: 683-691.

Deutsch, C.V. and Journel, A.G., 1998. *GSLIB: Geostatistical software library and user's guide*, second edition, Oxford University Press.

See Also

[show.vgms](#) to view the available models, [fit.variogram](#), [variogramLine](#), [variogram](#) for the sample variogram.

Examples

```
vgm()
vgm(10, "Exp", 300)
x <- vgm(10, "Exp", 300)
vgm(10, "Nug", 0)
vgm(10, "Exp", 300, 4.5)
vgm(10, "Mat", 300, 4.5, kappa = 0.7)
vgm( 5, "Exp", 300, add.to = vgm(5, "Exp", 60, nugget = 2.5))
vgm(10, "Exp", 300, anis = c(30, 0.5))
vgm(10, "Exp", 300, anis = c(30, 10, 0, 0.5, 0.3))
# Matern variogram model:
vgm(1, "Mat", 1, kappa=.3)
x <- vgm(0.39527463, "Sph", 953.8942, nugget = 0.06105141)
x
print(x, digits = 3);
# to see all components, do
print.data.frame(x)
vv=vgm(model = "Tab", covtable =
variogramLine(vgm(1, "Sph", 1), 1, n=1e4, min = 0, covariance = TRUE))
```

vgm.panel.xyplot *panel functions for most of the variogram plots through lattice*

Description

Variogram plots contain symbols and lines; more control over them can be gained by writing your own panel functions, or extending the ones described here; see examples.

Usage

```
vgm.panel.xyplot(x, y, subscripts, type = "p", pch = plot.symbol$pch,
  col, col.line = plot.line$col, col.symbol = plot.symbol$col,
  lty = plot.line$lty, cex = plot.symbol$cex, ids, lwd = plot.line$lwd,
  model = model, direction = direction, labels, shift = shift, mode = mode, ...)
panel.pointPairs(x, y, type = "p", pch = plot.symbol$pch, col, col.line =
  plot.line$col, col.symbol = plot.symbol$col, lty = plot.line$lty,
  cex = plot.symbol$cex, lwd = plot.line$lwd, pairs = pairs,
  line.pch = line.pch, ...)
```

Arguments

x	x coordinates of points in this panel
y	y coordinates of points in this panel
subscripts	subscripts of points in this panel
type	plot type: "l" for connected lines
pch	plotting symbol
col	symbol and line color (if set)
col.line	line color
col.symbol	symbol color
lty	line type for variogram model
cex	symbol size
ids	gstat model ids
lwd	line width
model	variogram model
direction	direction vector c(dir.horizontal, dir.ver)
labels	labels to plot next to points
shift	amount to shift the label right of the symbol
mode	to be set by calling function only
line.pch	symbol type to be used for point of selected point pairs, e.g. to highlight point pairs with distance close to zero
pairs	two-column matrix with pair indexes to be highlighted
...	parameters that get passed to lpoints

Value

ignored; the enclosing function returns a plot of class `trellis`

Author(s)

Edzer Pebesma

References

<http://www.gstat.org/>

See Also

[plot.gstatVariogram](#), [vgm](#)

Examples

```
library(lattice)
data(meuse)
coordinates(meuse) <- c("x", "y")
mypanel = function(x,y,...) {
  vgm.panel.xyplot(x,y,...)
  panel.abline(h=var(log(meuse$zinc)), color = 'red')
}
plot(variogram(log(zinc)~1,meuse), panel = mypanel)
```

 walker

Walker Lake sample and exhaustive data sets

Description

This is the Walker Lake data sets (sample and exhaustive data set), used in Isaaks and Srivastava's Applied Geostatistics.

Usage

```
data(walker)
```

Format

This data frame contains the following columns:

Id Identification Number

X Xlocation in meter

Y Ylocation in meter

V V variable, concentration in ppm

U U variable, concentration in ppm

T T variable, indicator variable

Note

This data sets were obtained from the data sets on <http://www.ai-geostats.org/>

References

Applied Geostatistics by Edward H. Isaaks, R. Mohan Srivastava; Oxford University Press.

Examples

```
data(walker)
summary(walker)
summary(walker.exh)
```

wind

Ireland wind data, 1961-1978

Description

Daily average wind speeds for 1961-1978 at 12 synoptic meteorological stations in the Republic of Ireland (Haslett and raftery 1989). Wind speeds are in knots (1 knot = 0.5418 m/s), at each of the stations in the order given in Fig.4 of Haslett and Raftery (1989, see below)

Usage

```
data(wind)
```

Format

data.frame wind contains the following columns:

year year, minus 1900

month month (number) of the year

day day

RPT average wind speed in knots at station RPT

VAL average wind speed in knots at station VAL

ROS average wind speed in knots at station ROS

KIL average wind speed in knots at station KIL

SHA average wind speed in knots at station SHA

BIR average wind speed in knots at station BIR

DUB average wind speed in knots at station DUB

CLA average wind speed in knots at station CLA

MUL average wind speed in knots at station MUL

CLO average wind speed in knots at station CLO

BEL average wind speed in knots at station BEL

MAL average wind speed in knots at station MAL

data.frame `wind.loc` contains the following columns:

Station Station name

Code Station code

Latitude Latitude, in DMS, see examples below

Longitude Longitude, in DMS, see examples below

MeanWind mean wind for each station, metres per second

Note

This data set comes with the following message: “Be aware that the dataset is 532494 bytes long (thats over half a Megabyte). Please be sure you want the data before you request it.”

The data were obtained on Oct 12, 2008, from: <http://www.stat.washington.edu/raftery/software.html>

The data are also available from statlib.

Locations of 11 of the stations (ROS, Rosslare has been thrown out because it fits poorly the spatial correlations of the other stations) were obtained from: <http://www.stat.washington.edu/research/reports/2005/tr475.pdf>

Rosslare lat/lon was obtained from google maps, location Rosslare. The mean wind value for Rosslare comes from Fig. 1 in the original paper.

Haslett and Raftery proposed to use a sqrt-transform to stabilize the variance.

Author(s)

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References

These data were analyzed in detail in the following article:

Haslett, J. and Raftery, A. E. (1989). Space-time Modelling with Long-memory Dependence: Assessing Ireland’s Wind Power Resource (with Discussion). *Applied Statistics* 38, 1-50.

and in many later papers on space-time analysis, for example:

Tilmann Gneiting, Marc G. Genton, Peter Guttorp: Geostatistical Space-Time Models, Stationarity, Separability and Full symmetry. Ch. 4 in: B. Finkenstaedt, L. Held, V. Isham, *Statistical Methods for Spatio-Temporal Systems*.

Examples

```
data(wind)
summary(wind)
wind.loc
wind.loc$y = as.numeric(char2dms(as.character(wind.loc[["Latitude"]]))))
wind.loc$x = as.numeric(char2dms(as.character(wind.loc[["Longitude"]]))))
coordinates(wind.loc) = ~x+y
# fig 1:
if (require(mapdata)) {
  map("worldHires", xlim = c(-11,-5.4), ylim = c(51,55.5))
}
```

```

    plot(wind.loc, add=TRUE, pch=16)
    text(coordinates(wind.loc), pos=1, label=wind.loc$Station)
}
wind$time = ISOdate(wind$year+1900, wind$month, wind$day)
# time series of e.g. Dublin data:
plot(DUB~time, wind, type='l', ylab = "windspeed (knots)", main = "Dublin")

# fig 2:
#wind = wind[!(wind$month == 2 & wind$day == 29),]
wind$jday = as.numeric(format(wind$time, '%j'))
windsqrt = sqrt(0.5148 * wind[4:15])
Jday = 1:366
daymeans = apply(sapply(split(windsqrt - mean(windsqrt), wind$jday), mean), 2, mean)
plot(daymeans ~ Jday)
lines(lowess(daymeans ~ Jday, f = 0.1))

# subtract the trend:
meanwind = lowess(daymeans ~ Jday, f = 0.1)$y[wind$jday]
velocity = apply(windsqrt, 2, function(x) { x - meanwind })

# match order of columns in wind to Code in wind.loc:
pts = coordinates(wind.loc[match(names(wind[4:15]), wind.loc$Code),])

# fig 3, but not really yet...
dists = spDists(pts, longlat=TRUE)
corv = cor(velocity)
sel = !(as.vector(dists) == 0)
plot(as.vector(corv[sel]) ~ as.vector(dists[sel]),
     xlim = c(0,500), ylim = c(.4, 1), xlab = "distance (km.)",
     ylab = "correlation")
# plots all points twice, ignores zero distance

# now really get fig 3:
ros = rownames(corv) == "ROS"
dists.nr = dists[!ros,!ros]
corv.nr = corv[!ros,!ros]
sel = !(as.vector(dists.nr) == 0)
plot(as.vector(corv.nr[sel]) ~ as.vector(dists.nr[sel]), pch = 3,
     xlim = c(0,500), ylim = c(.4, 1), xlab = "distance (km.)",
     ylab = "correlation")
# add outlier:
points(corv[ros,!ros] ~ dists[ros,!ros], pch=16, cex=.5)
xdiscr = 1:500
# add correlation model:
lines(xdiscr, .968 * exp(- .00134 * xdiscr))

```

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